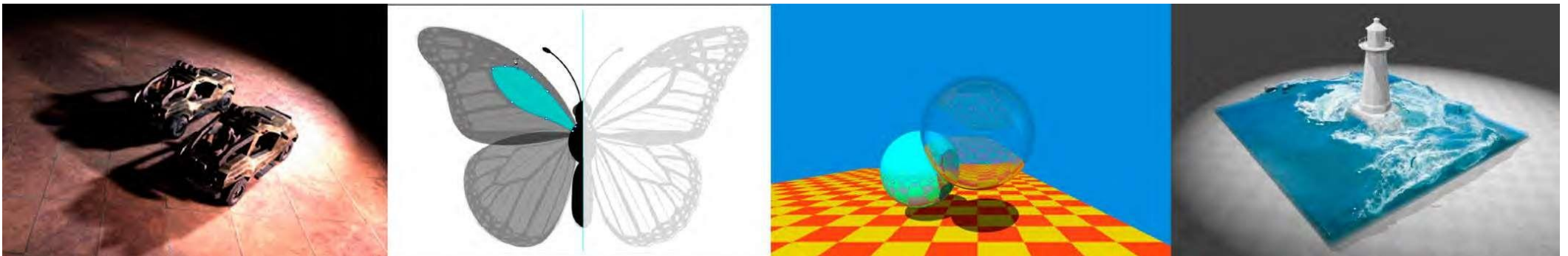


Computer Graphics

Shading (Texture Mapping cont.)



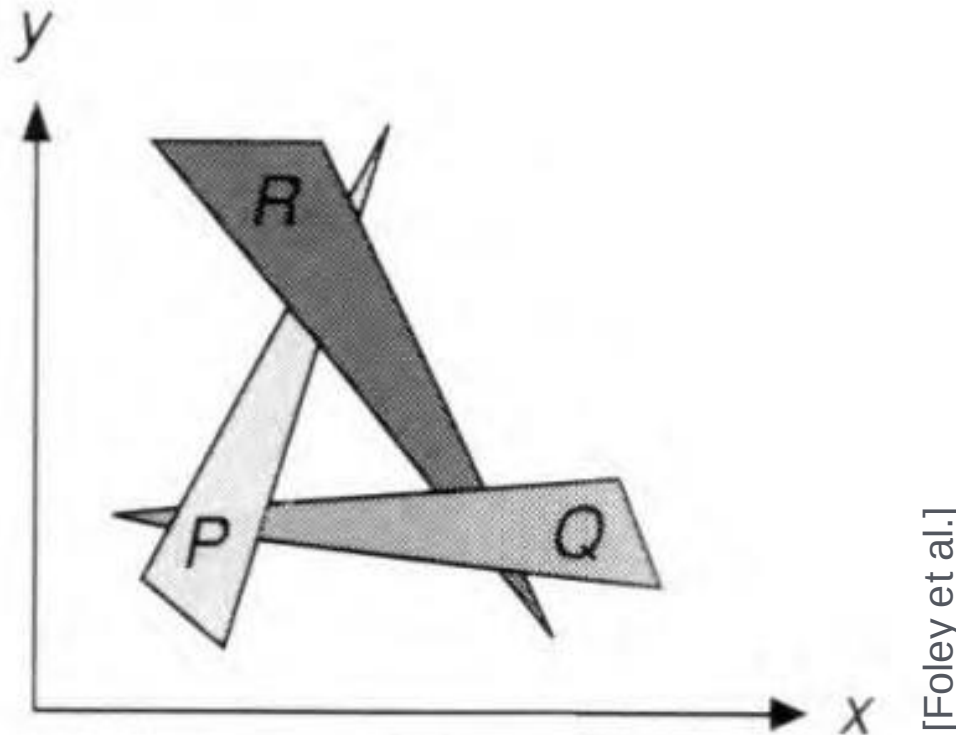
Last Lectures

- Visibility / occlusion
 - Z-buffering
- Shading
 - Blinn-Phong reflectance model
 - At a specific shading point
 - Shading frequencies
 - Graphics pipeline
 - Texture mapping
 - Barycentric coordinates

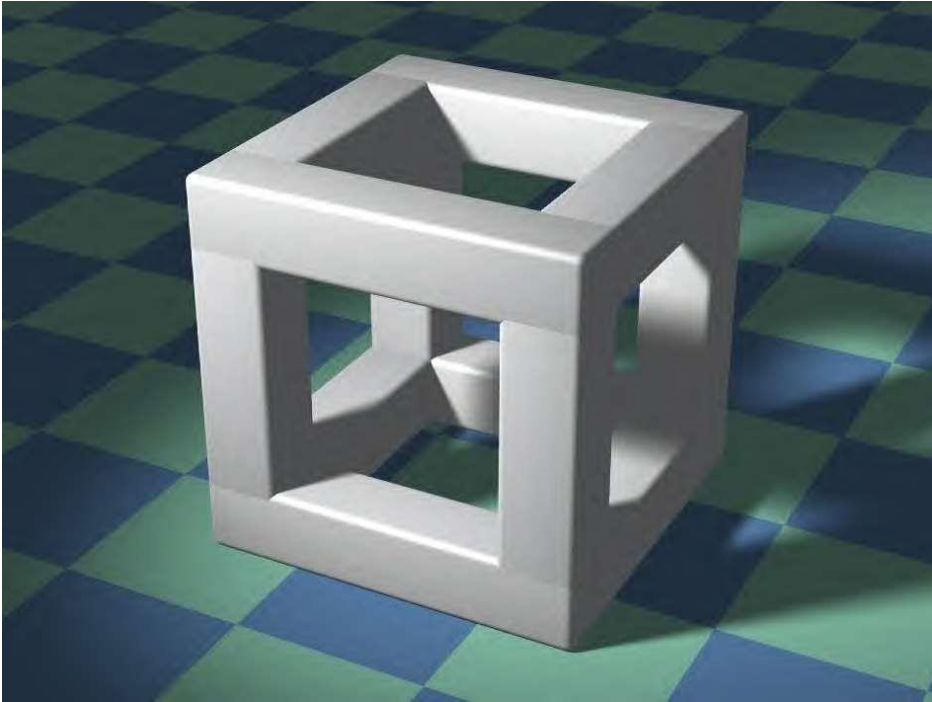
Painter's Algorithm

Requires sorting in depth ($O(n \log n)$ for n triangles)

Can have unresolvable depth order



Z-Buffer Example



Rendering



Depth / Zbuffer

Image source: Dominic Alves, flickr.

Z-Buffer Complexity

Complexity

- $O(n)$ for n triangles (assuming constant coverage)
- How is it possible to sort n triangles in linear time?

Drawing triangles in different orders?

Most important visibility algorithm

- Implemented in hardware for all GPUs

Shading: Definition

- ✱ In Merriam-Webster Dictionary

shad·ing, ['ʃeɪdɪŋ], noun

The darkening or coloring of an illustration or diagram with parallel lines or a block of color.

使用平行线或色块使得插图或图案变暗或着色

- ✱ In this course

The process of **applying a material** to an object.

Perceptual Observations



Specular highlights

高光

Diffuse reflection

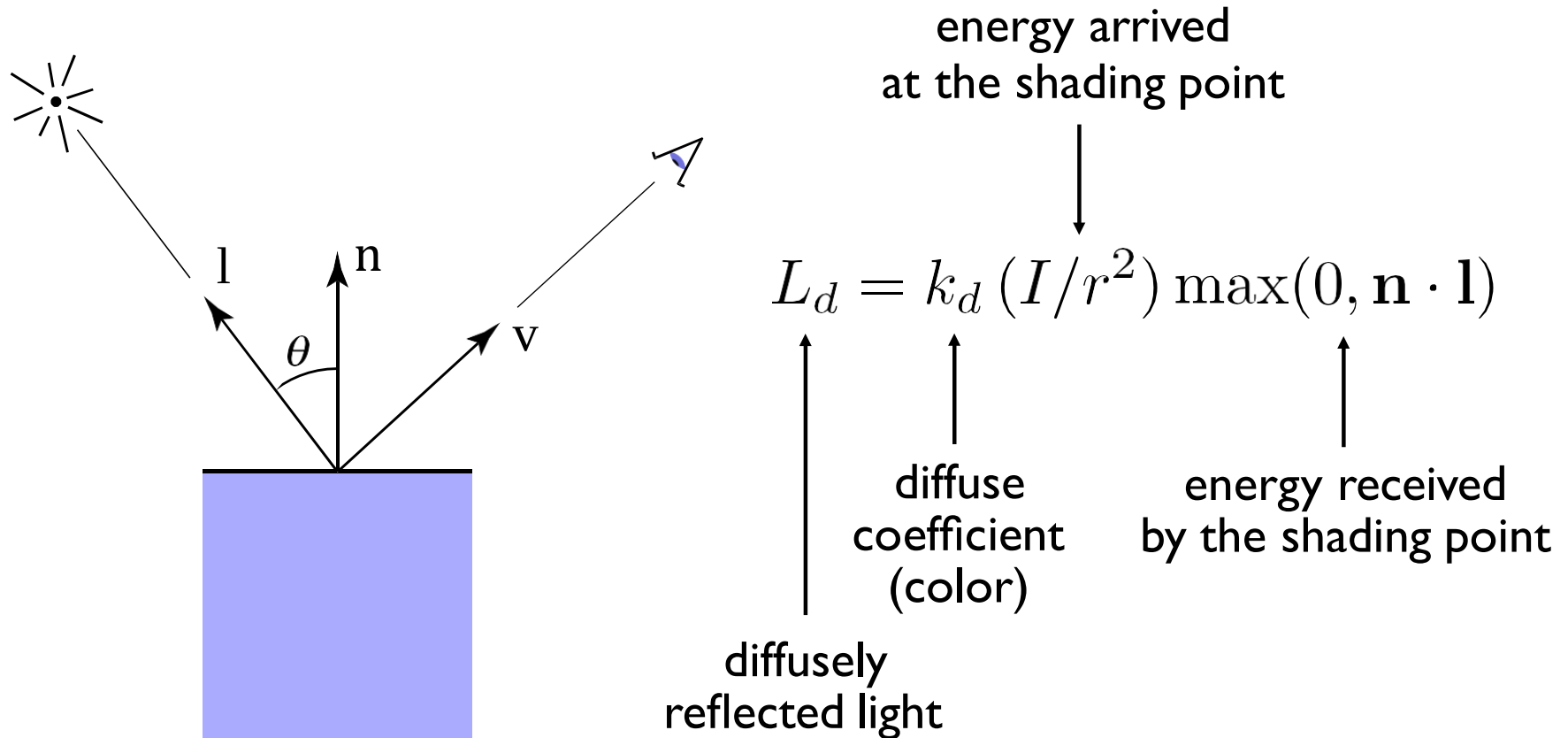
漫反射

Ambient lighting

环境光

Lambertian (Diffuse) Shading

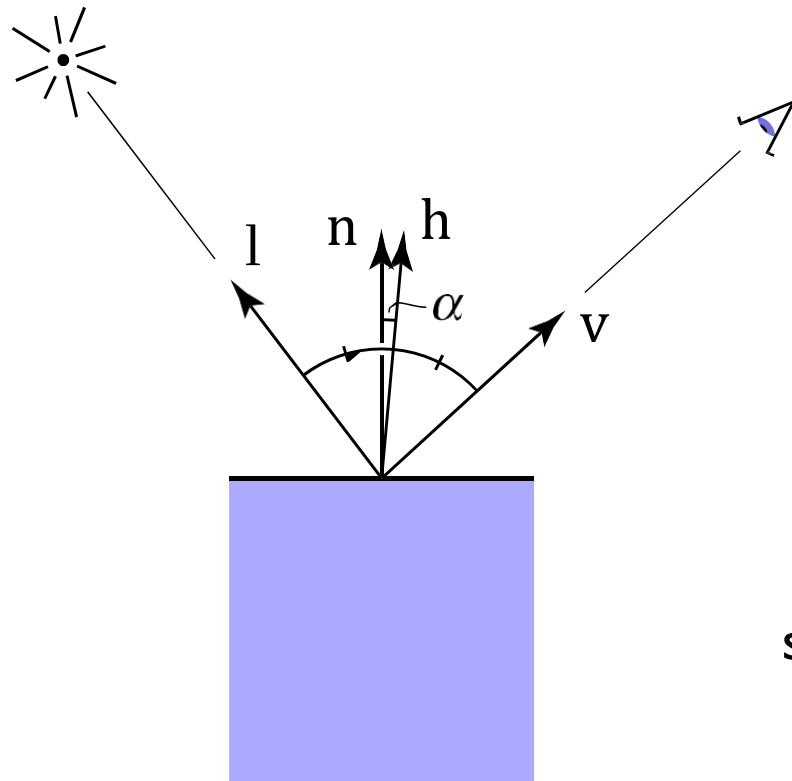
Shading **independent** of view direction



Specular Term (Blinn-Phong)

V close to mirror direction $\Leftrightarrow$ half vector near normal

- Measure “near” by dot product of unit vectors



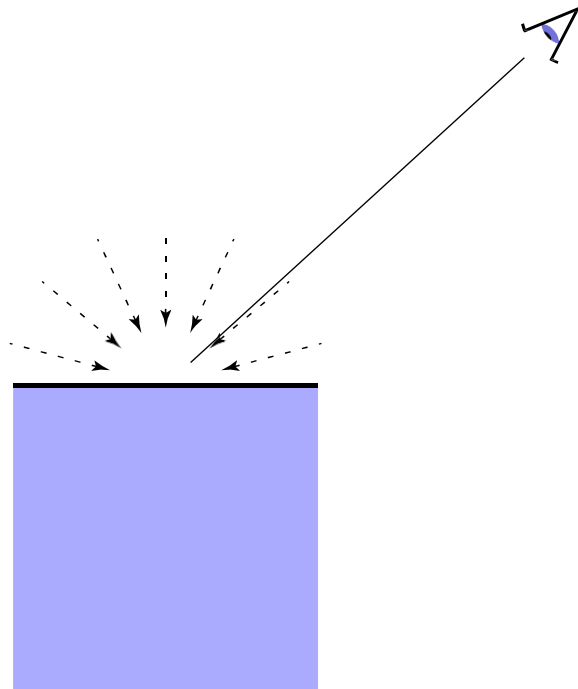
$$\begin{aligned}\mathbf{h} &= \text{bisector}(\mathbf{v}, \mathbf{l}) \\ &\text{(半程向量)} \\ &= \frac{\mathbf{v} + \mathbf{l}}{\|\mathbf{v} + \mathbf{l}\|}\end{aligned}$$

$$\begin{aligned}L_s &= k_s (I/r^2) \max(0, \cos \alpha)^p \\ &\quad \uparrow \\ &\text{specularly reflected light} \\ &\quad \uparrow \\ &\text{specular coefficient} \\ &= k_s (I/r^2) \max(0, \mathbf{n} \cdot \mathbf{h})^p\end{aligned}$$

Ambient Term

Shading that does not depend on anything

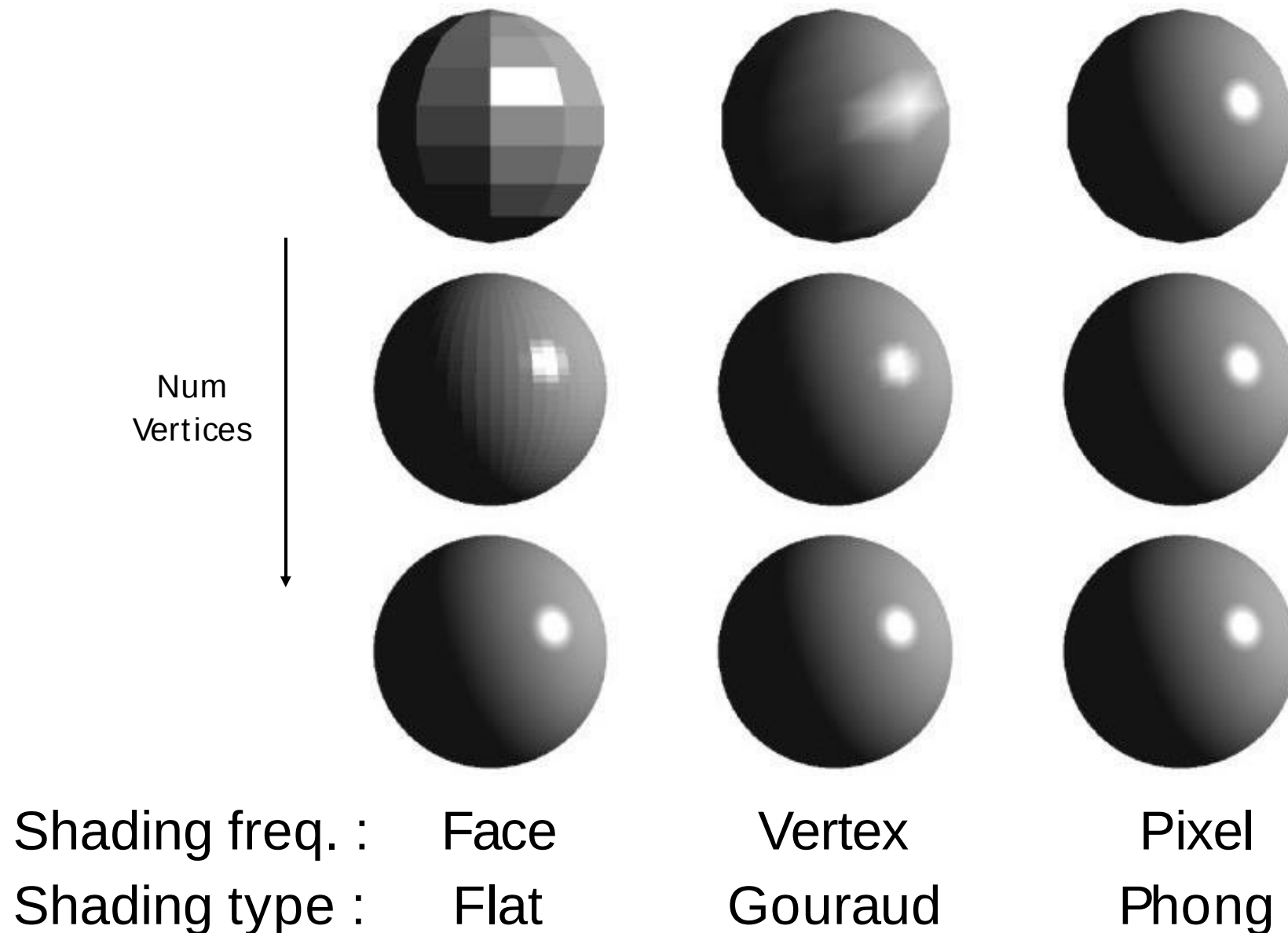
- Add constant color to account for disregarded illumination and fill in black shadows
- This is approximate / fake!



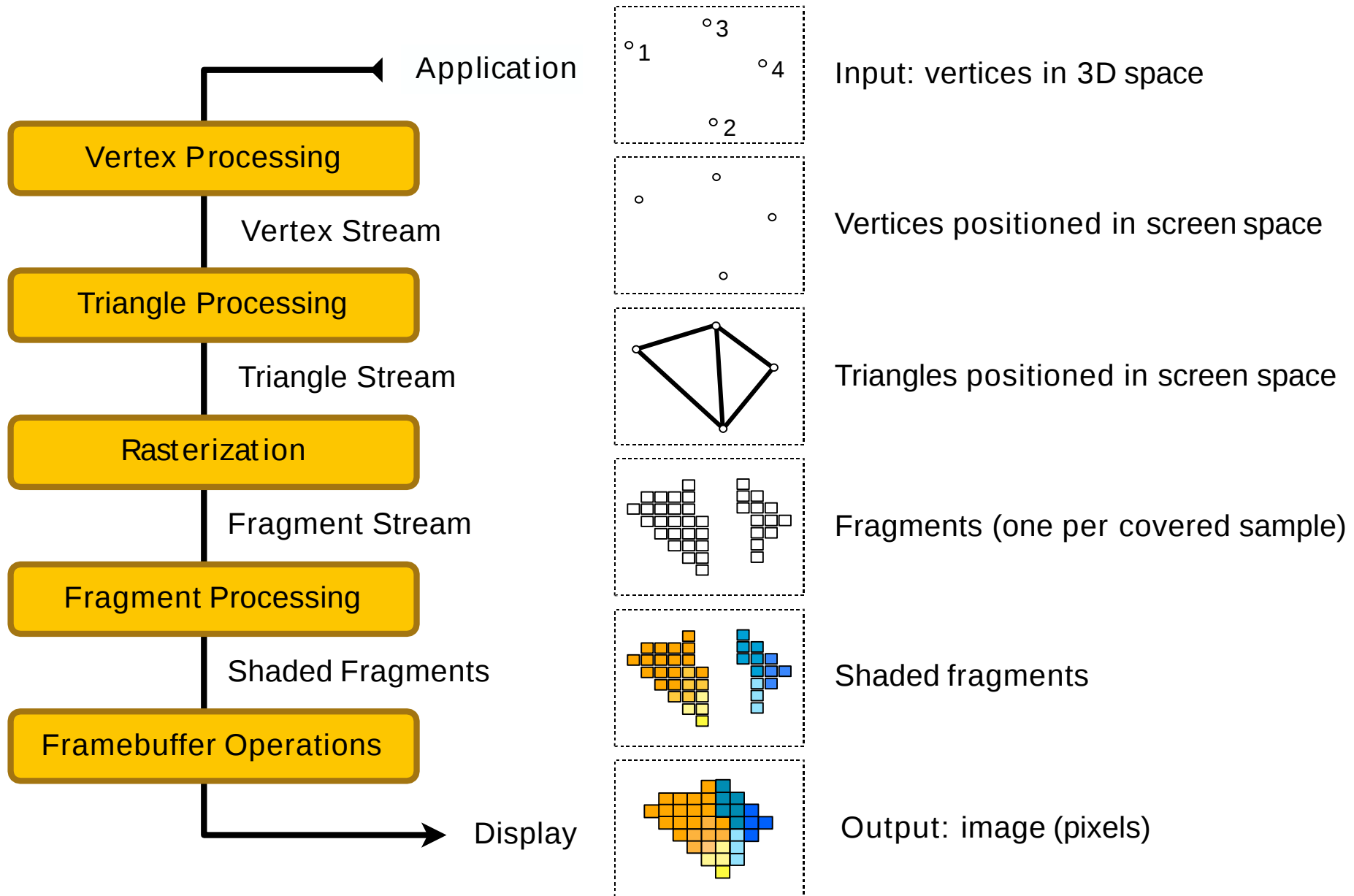
$$L_a = k_a I_a$$

↑ ↑
reflected ambient
ambient light coefficient

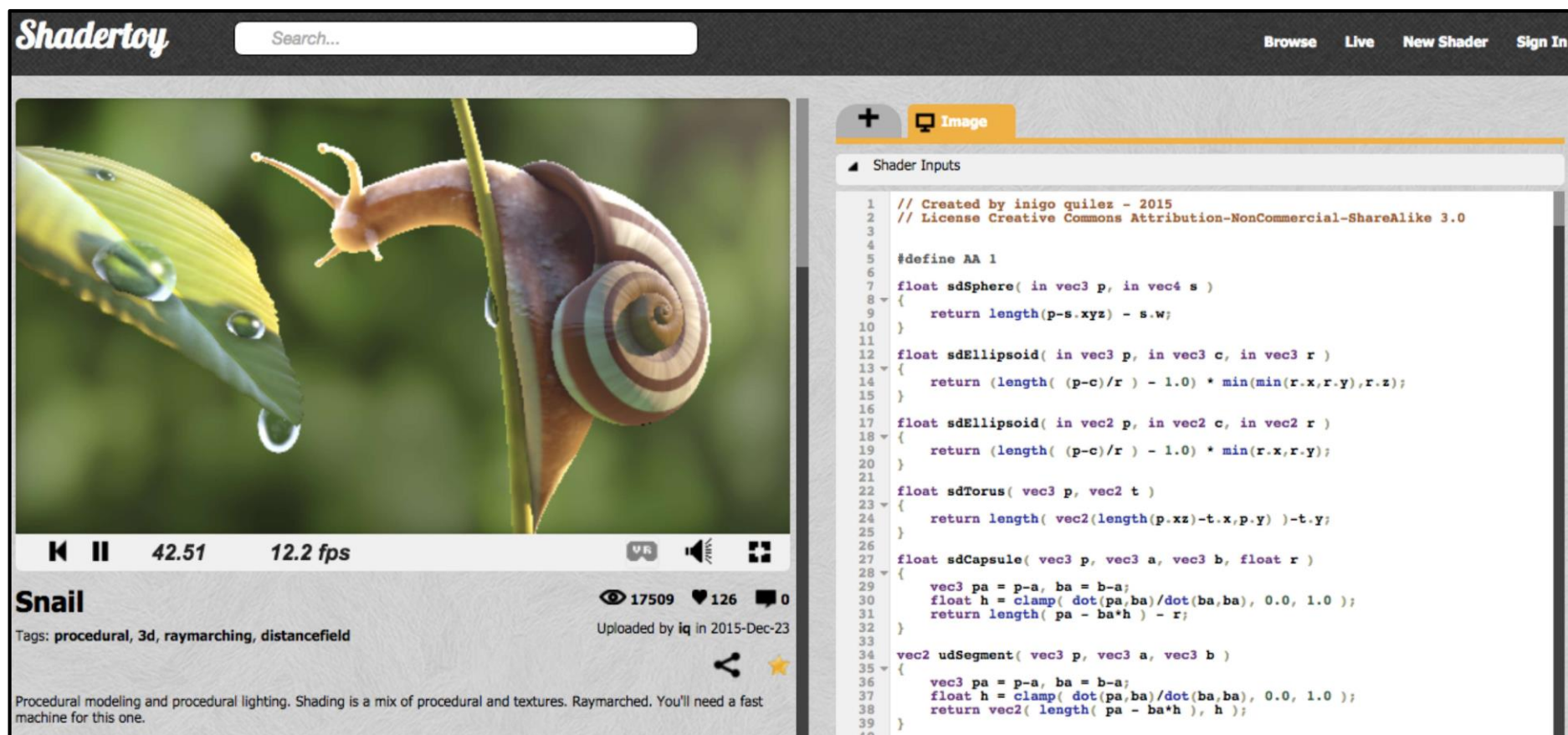
Shading Frequency: Face, Vertex or Pixel



Graphics Pipeline



Snail Shader Program



Inigo Quilez

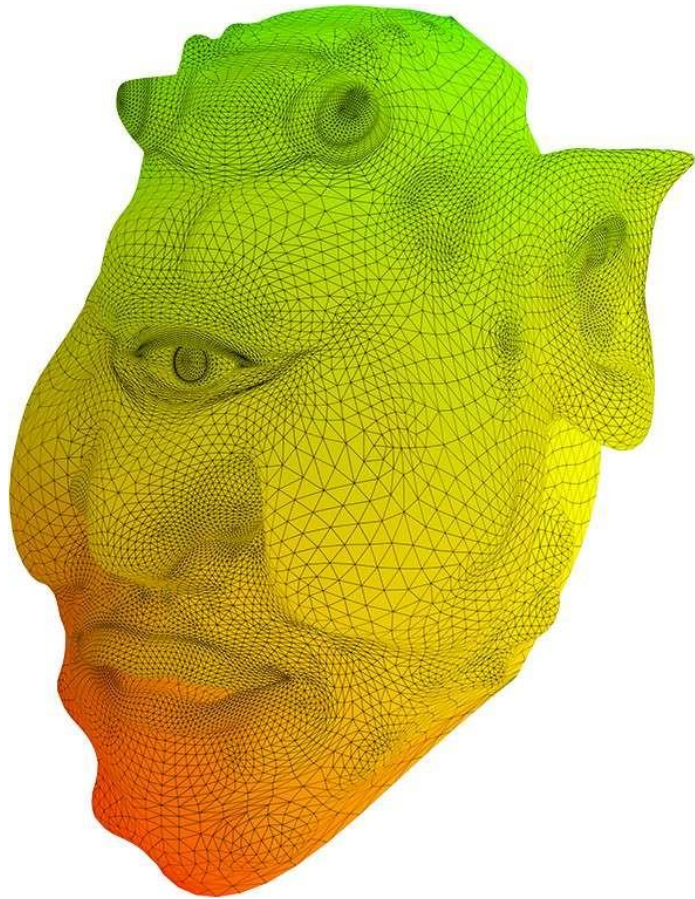
Procedurally modeled, 800 line shader.

<http://shadertoy.com/view/ld3Gz2>

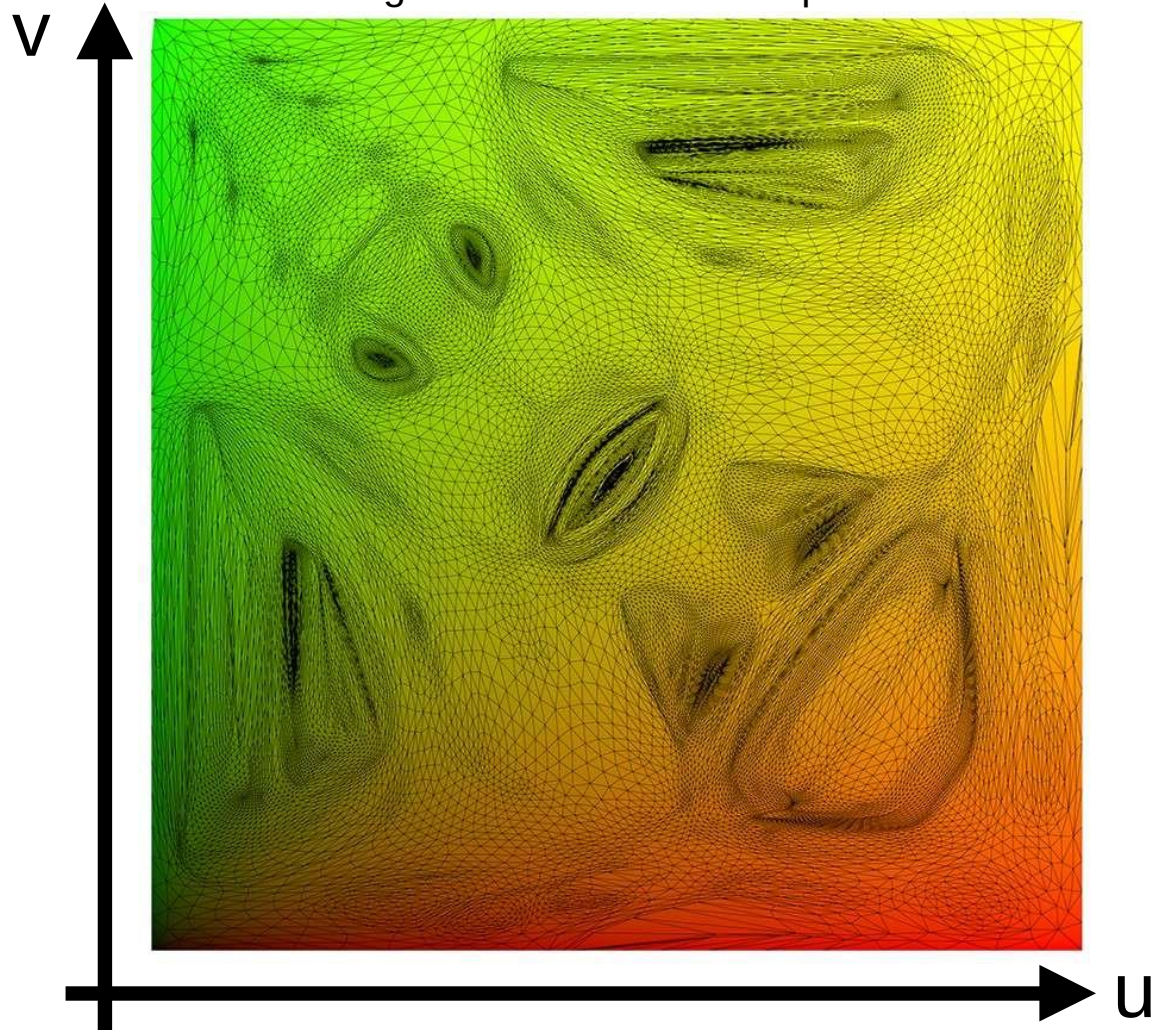
Visualization of Texture Coordinates

Each triangle vertex is assigned a texture coordinate (u,v)

Visualization of texture coordinates



Triangle vertices in texture space



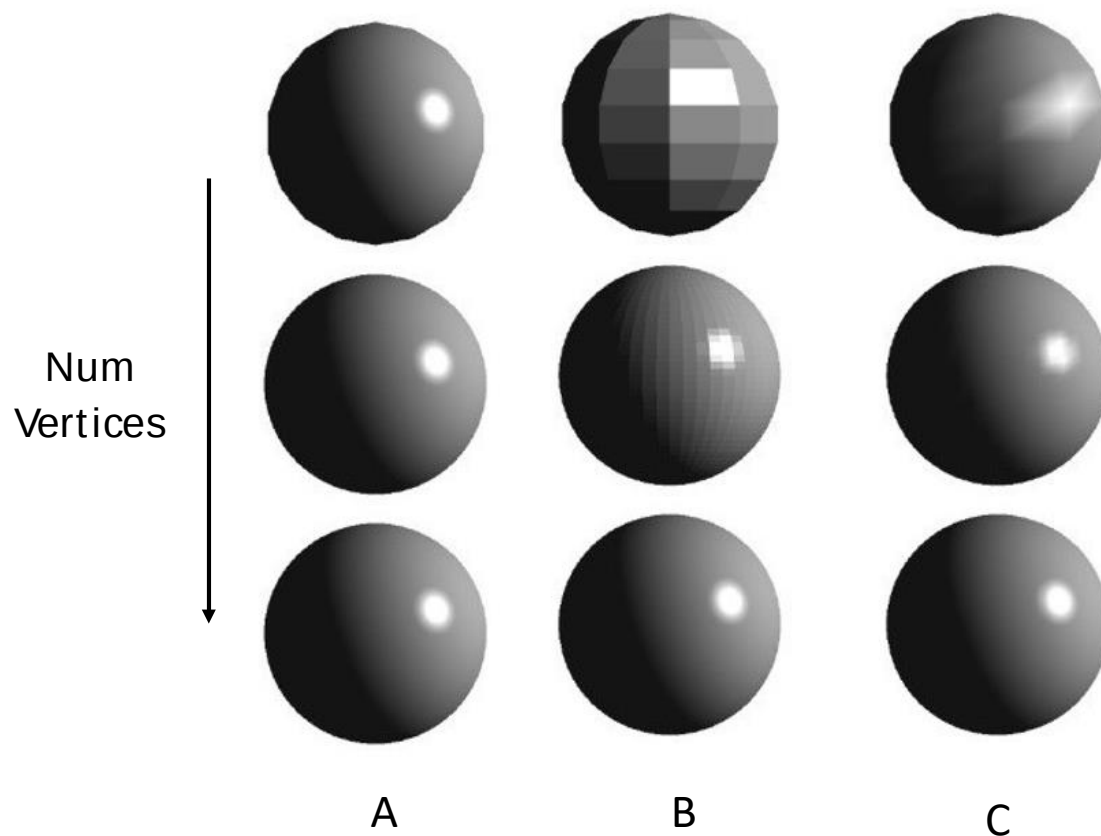
Bisector vector (半程向量)出现在Blinn-Phong模型的?

- ☐ A Ambient term
- ☐ B Diffusion term
- ☒ C Specular term
- ☐ D Phong term

提交

描述着色频率的示意图中，空格ABC处应该依次填？

- ☐ A Face, Vertex, Pixel
- ☐ B Vertex, Pixel, Face
- ☐ C Face, Pixel, Vertex
- ☒ D Pixel, Face, Vertex



提交

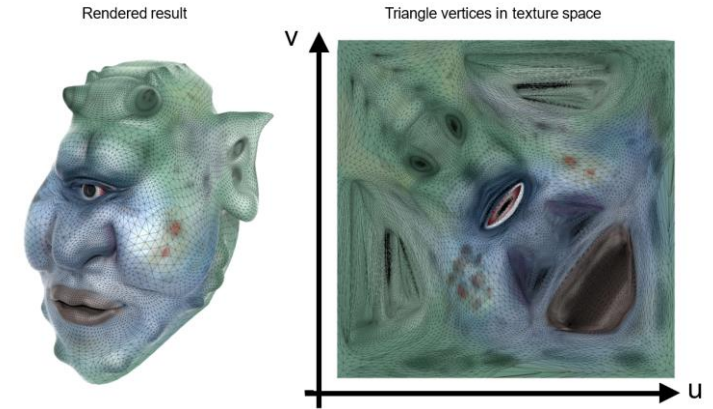
Interpolation Across Triangles: Barycentric Coordinates

(重心坐标)

Interpolation Across Triangles

Why do we want to interpolate?

- Specify values at vertices
- Obtain smoothly varying values across triangles



What do we want to interpolate?

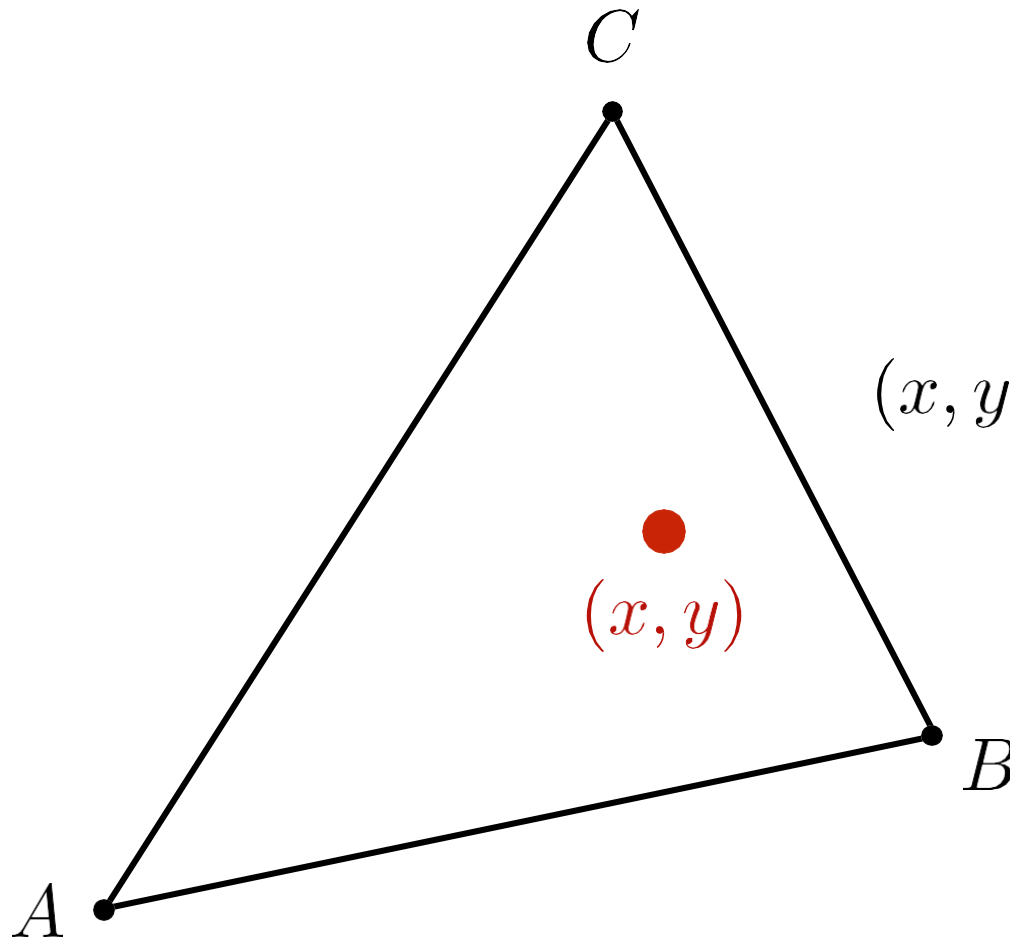
- Texture coordinates, colors, normal vectors, ...

How do we interpolate?

- Barycentric coordinates

Barycentric Coordinates

A coordinate system for triangles (α, β, γ)



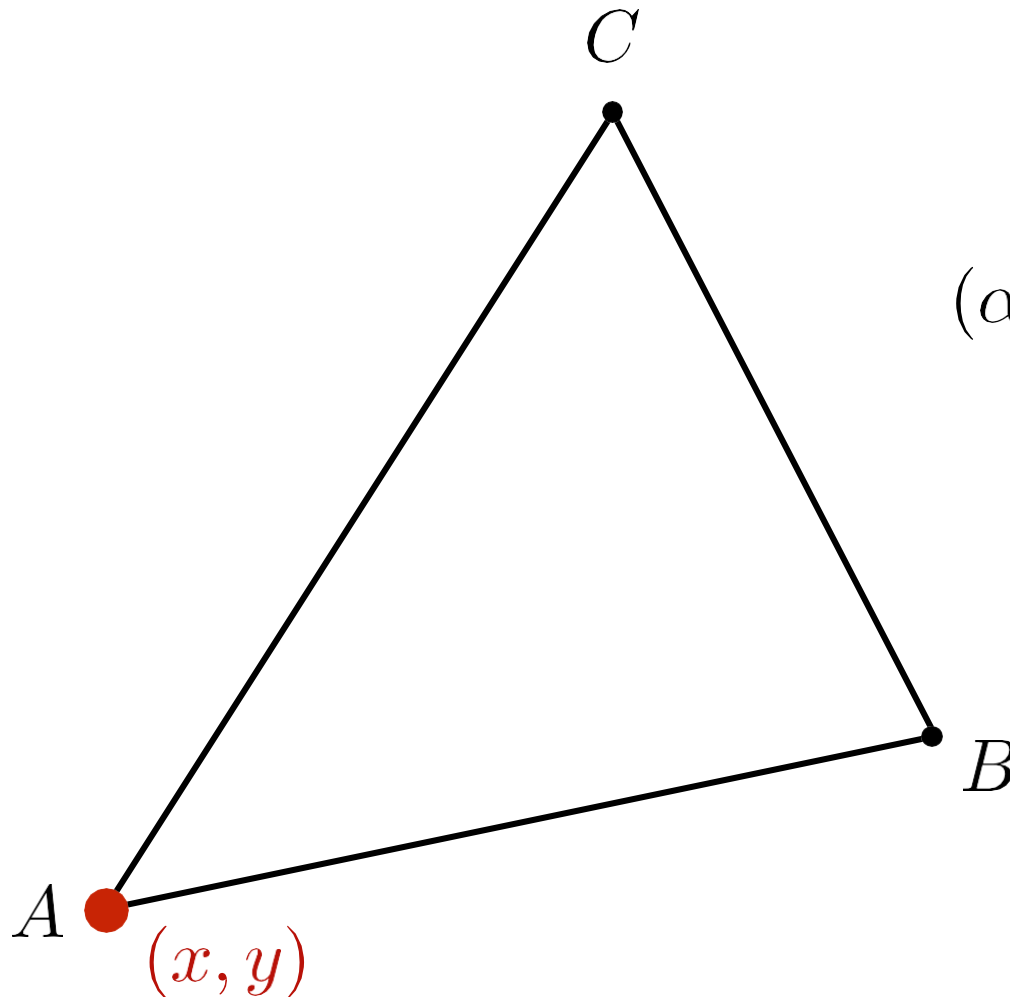
$$(x, y) = \alpha A + \beta B + \gamma C$$

$$\alpha + \beta + \gamma = 1$$

Inside the triangle if
all three coordinates
are non-negative

Barycentric Coordinates

What's the barycentric coordinate of A?

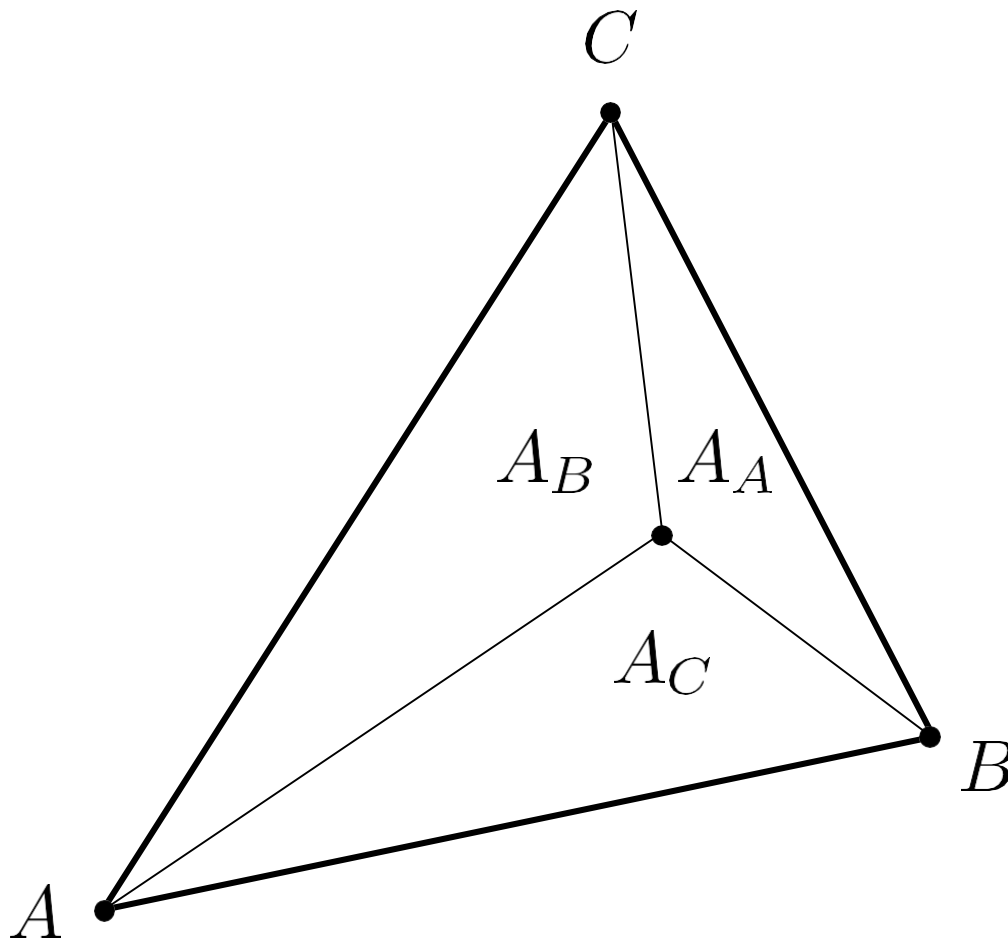


$$(\alpha, \beta, \gamma) = (1, 0, 0)$$

$$(x, y) = \alpha A + \beta B + \gamma C$$
$$= A$$

Barycentric Coordinates

Geometric viewpoint — proportional areas



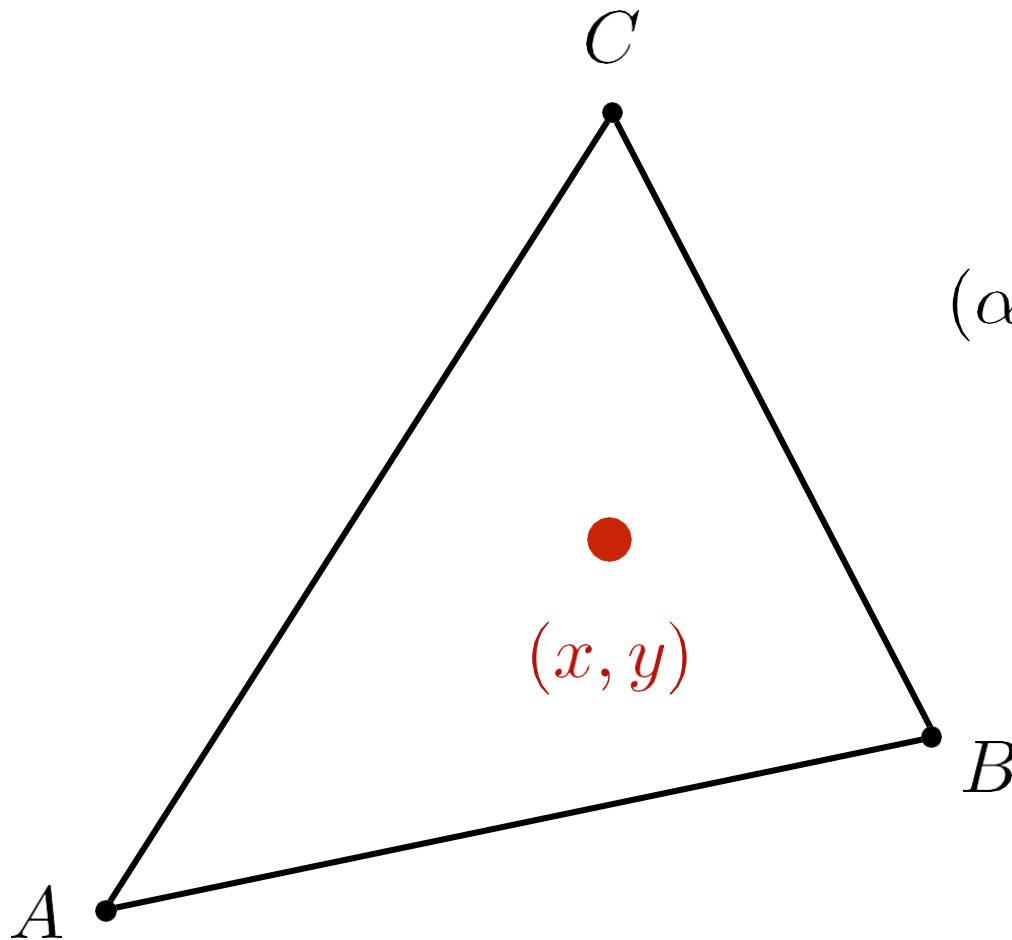
$$\alpha = \frac{A_A}{A_A + A_B + A_C}$$

$$\beta = \frac{A_B}{A_A + A_B + A_C}$$

$$\gamma = \frac{A_C}{A_A + A_B + A_C}$$

Barycentric Coordinates

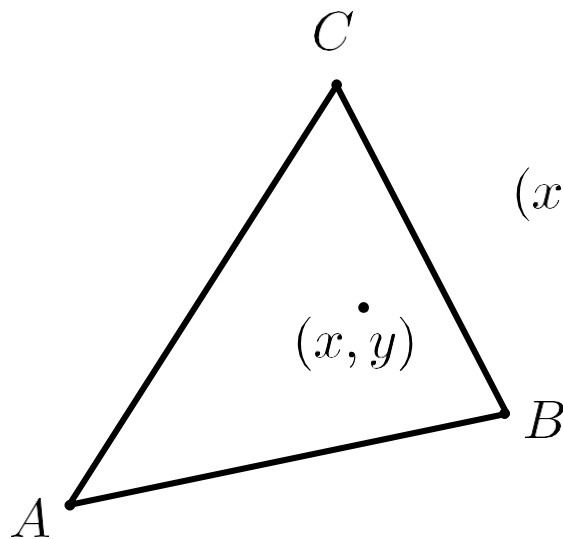
What's the barycentric coordinate of the centroid?



$$(\alpha, \beta, \gamma) = \left(\frac{1}{3}, \frac{1}{3}, \frac{1}{3}\right)$$

$$(x, y) = \frac{1}{3} A + \frac{1}{3} B + \frac{1}{3} C$$

Barycentric Coordinates: Formulas



$$(x, y) = \alpha A + \beta B + \gamma C$$

$$\alpha + \beta + \gamma = 1$$

$$\alpha = \frac{-(x - x_B)(y_C - y_B) + (y - y_B)(x_C - x_B)}{-(x_A - x_B)(y_C - y_B) + (y_A - y_B)(x_C - x_B)}$$

$$\beta = \frac{-(x - x_C)(y_A - y_C) + (y - y_C)(x_A - x_C)}{-(x_B - x_C)(y_A - y_C) + (y_B - y_C)(x_A - x_C)}$$

$$\gamma = 1 - \alpha - \beta$$

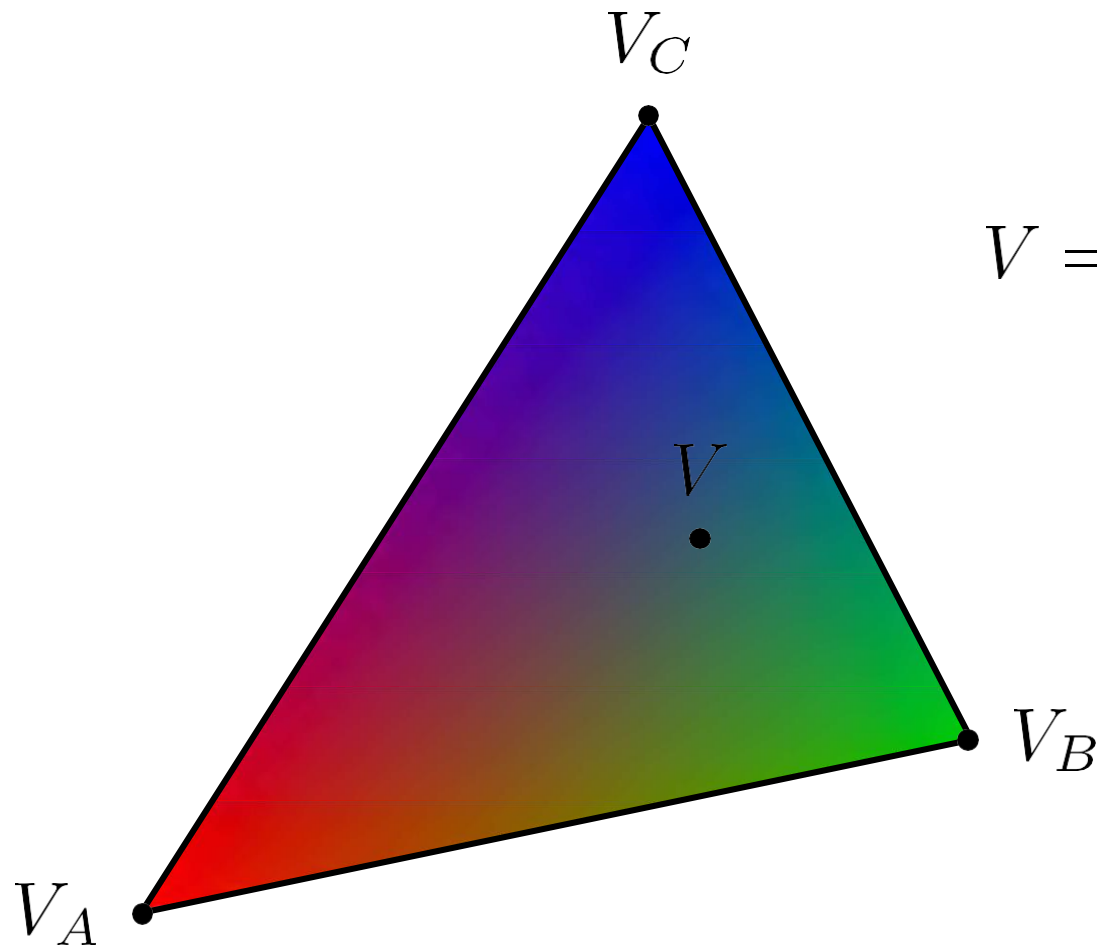
~~~~~  
 $A(x_1, y_1), B(x_2, y_2), C(x_3, y_3)$  , 平移后有

$A(0, 0), B(x_2 - x_1, y_2 - y_1), C(x_3 - x_1, y_3 - y_1)$  , 则有:

$$S_{\Delta ABC} = \frac{1}{2} |(x_2 - x_1)(y_3 - y_1) - (y_2 - y_1)(x_3 - x_1)| = \frac{1}{2} |x_1 y_2 + x_2 y_3 + x_3 y_1 - x_2 y_1 - x_3 y_2 - x_1 y_3|$$

# Using Barycentric Coordinates

Linearly interpolate values at vertices



$$V = \alpha V_A + \beta V_B + \gamma V_C$$

$V_A$ ,  $V_B$ ,  $V_C$  can be  
positions, texture  
coordinates, color,  
normal, depth,  
material attributes...

However, barycentric coordinates are not invariant under projection!

# Generalized Barycentric Coordinates

These coordinates have been later generalized to support simple polygons in 2D and polyhedra in 3D.

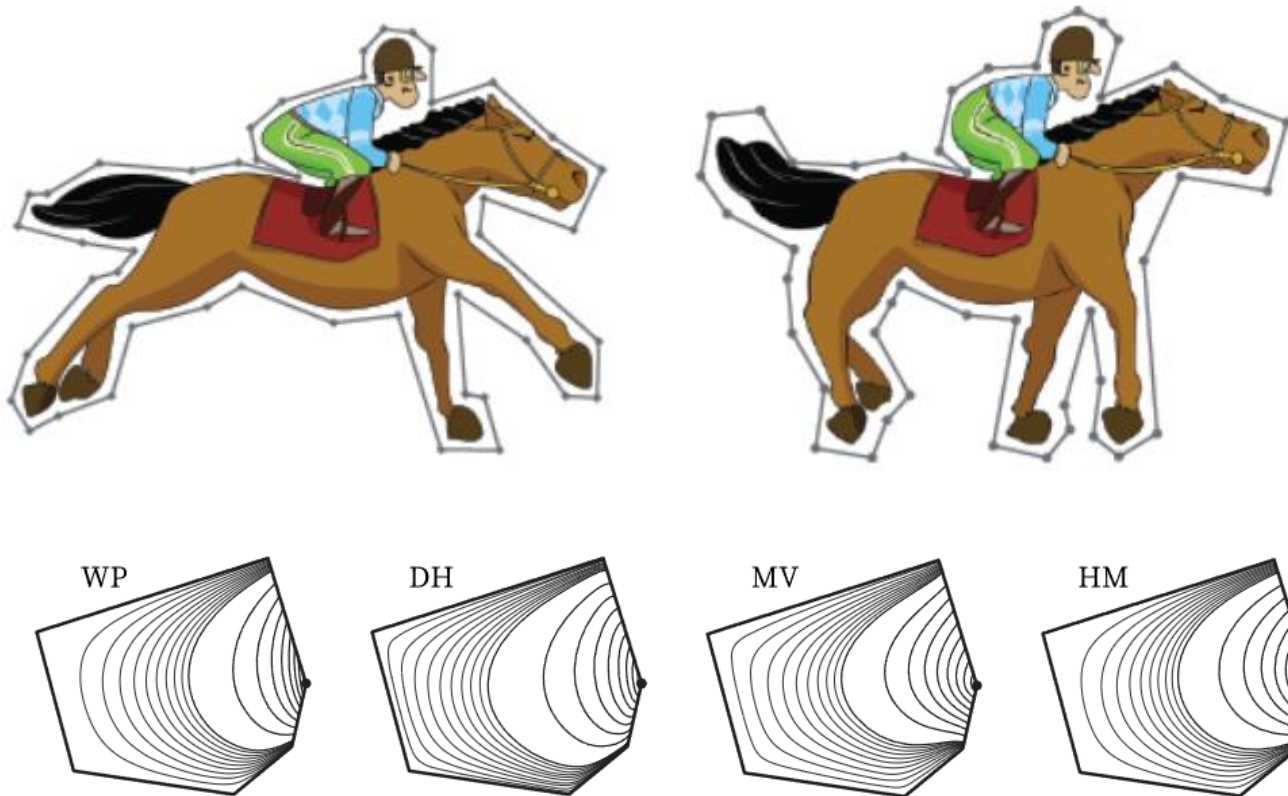


Figure 101.1 Wachspress (WP), discrete harmonic (DH), mean value (MV), and harmonic (HM) coordinate functions for a convex polygon plotted with respect to the marked vertex.

# Applying Textures

# Simple Texture Mapping: Diffuse Color

Usually a pixel's center

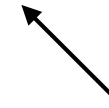


for each rasterized screen sample  $(x,y)$ :

$(u,v)$  = evaluate texture coordinate at  $(x,y)$

texcolor = `texture.sample(u,v)`;

set sample's color to texcolor;



Using barycentric  
coordinates!



Usually the diffuse albedo  $K_d$   
(recall the Blinn-Phong reflectance model)

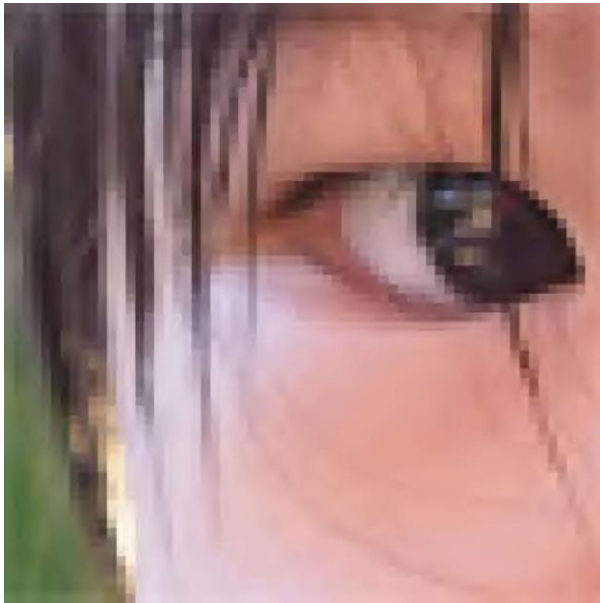
# Texture Magnification

(What if the texture is too small?)

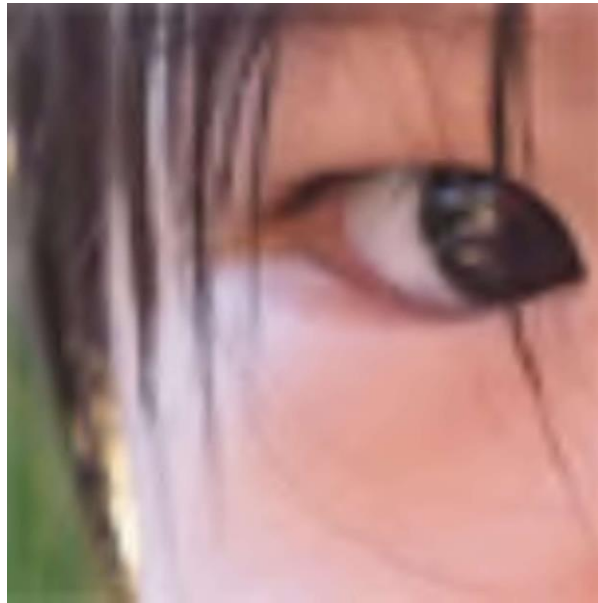
# Texture Magnification - Easy Case

Generally don't want this — insufficient texture resolution

A pixel on a texture — a texel (纹理元素、纹素)



Nearest

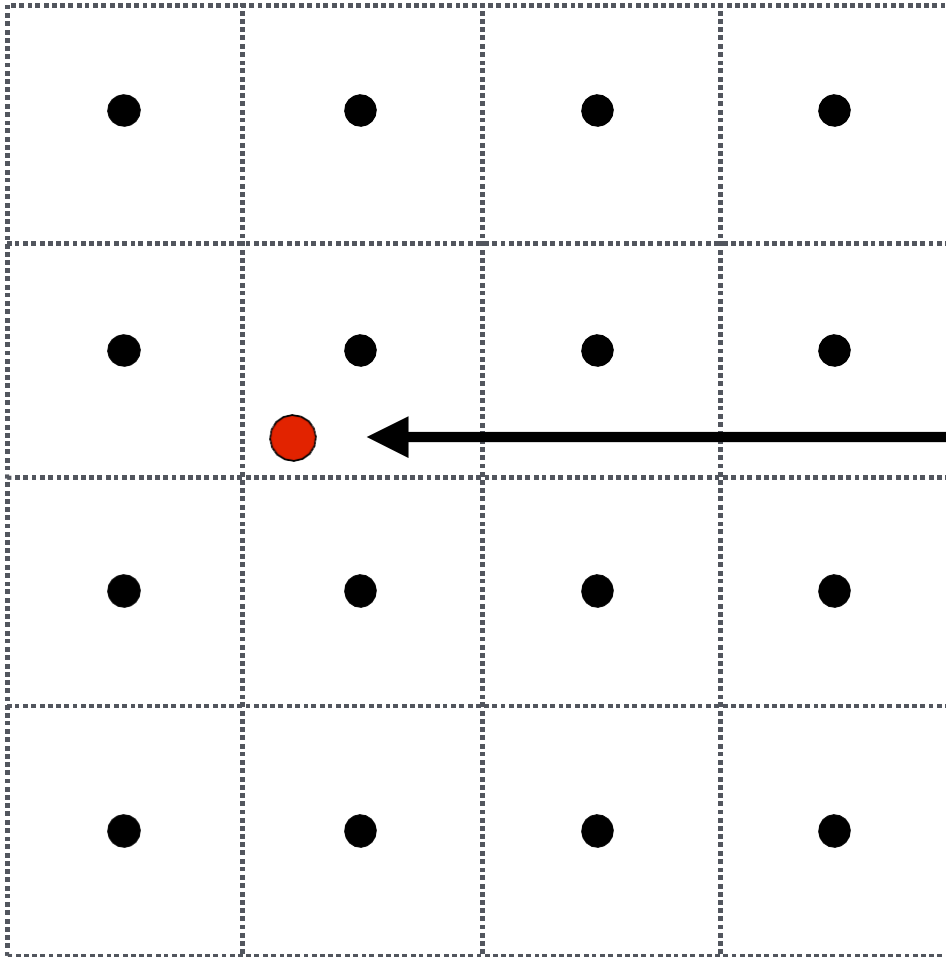


Bilinear



Bicubic

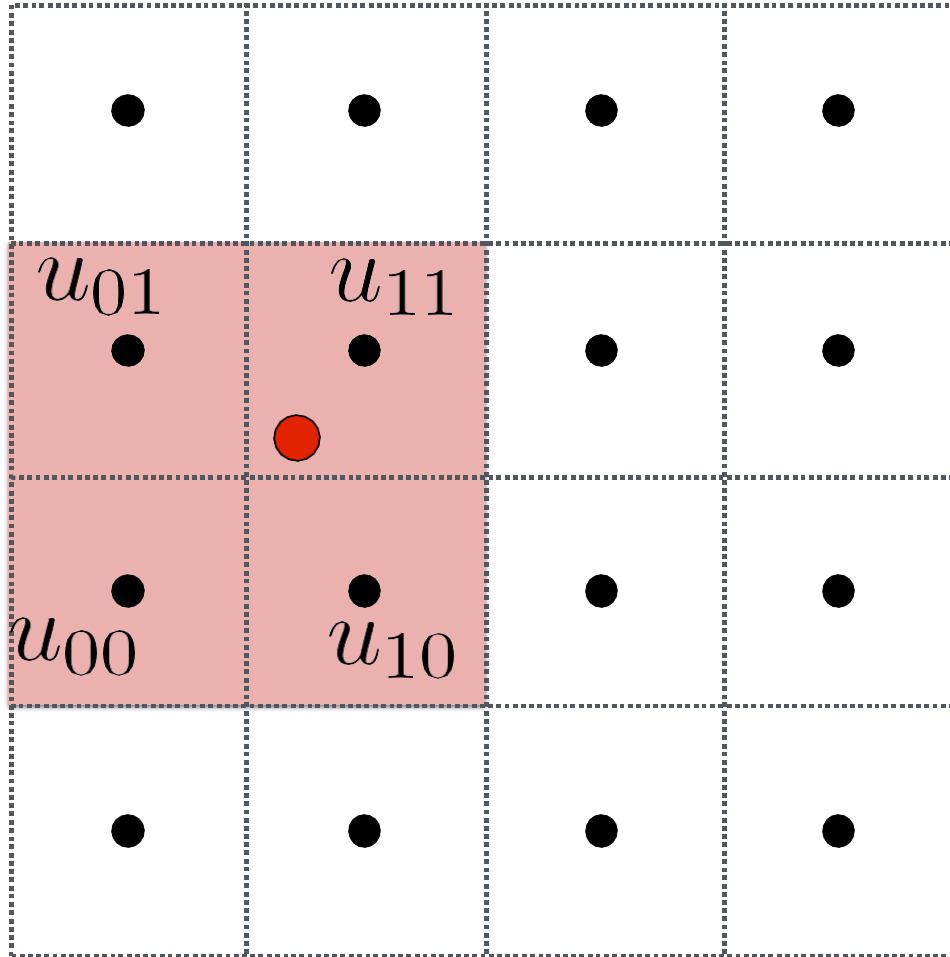
# Bilinear Interpolation



Want to sample  
texture value  $f(x,y)$  at  
red point

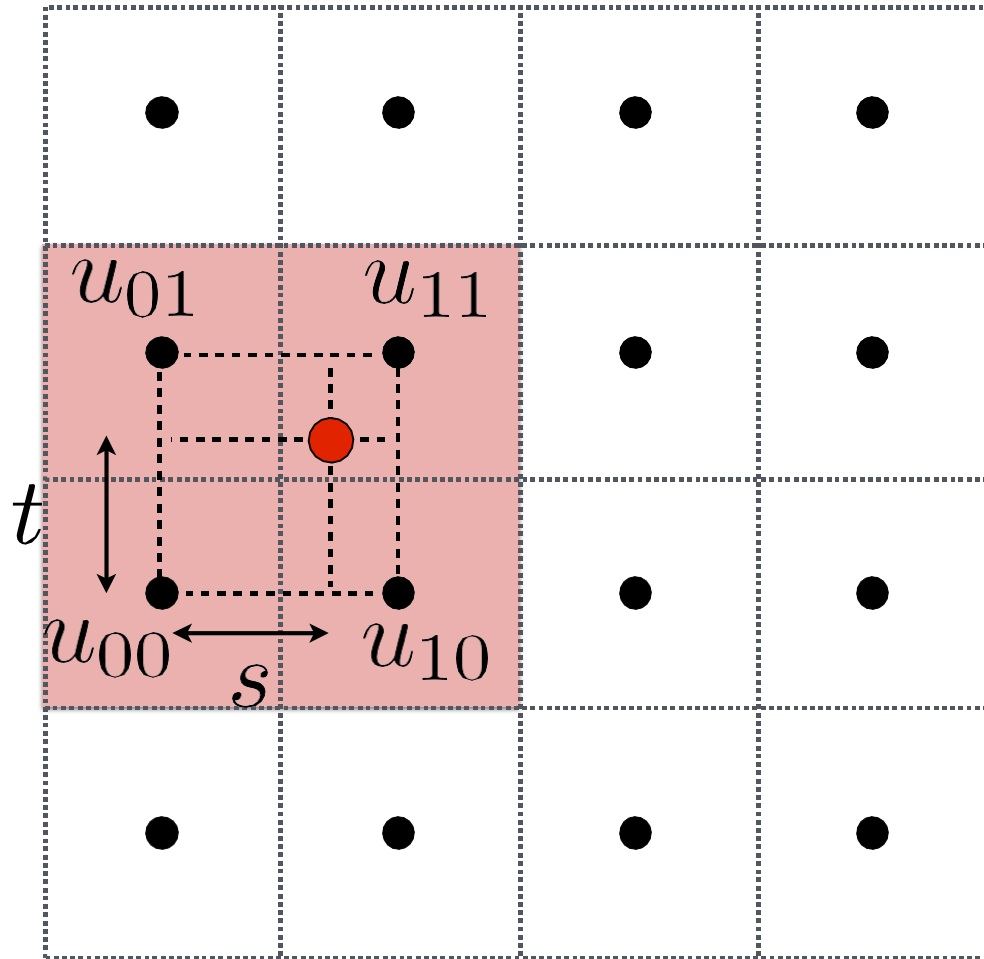
Black points indicate  
texture sample  
locations

# Bilinear Interpolation



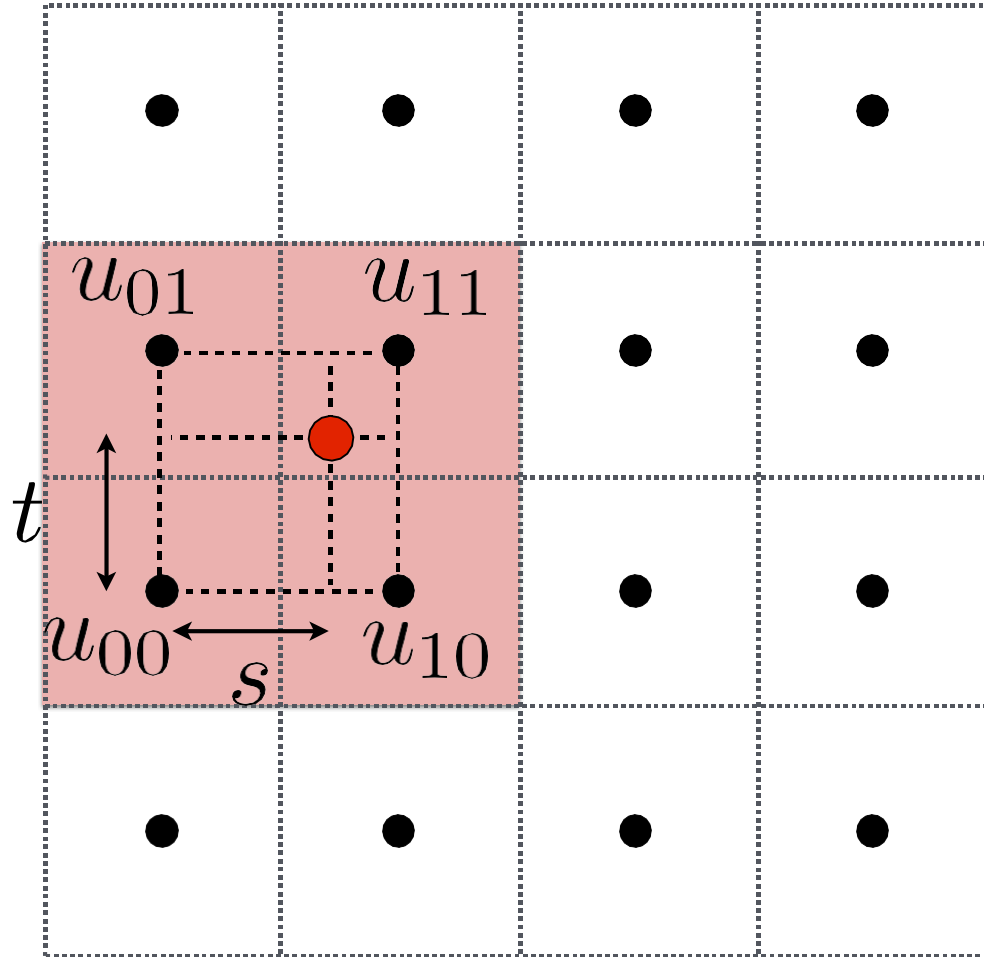
Take 4 nearest sample locations, with texture values as labeled.

# Bilinear Interpolation



And fractional offsets,  
( $s, t$ ) as shown

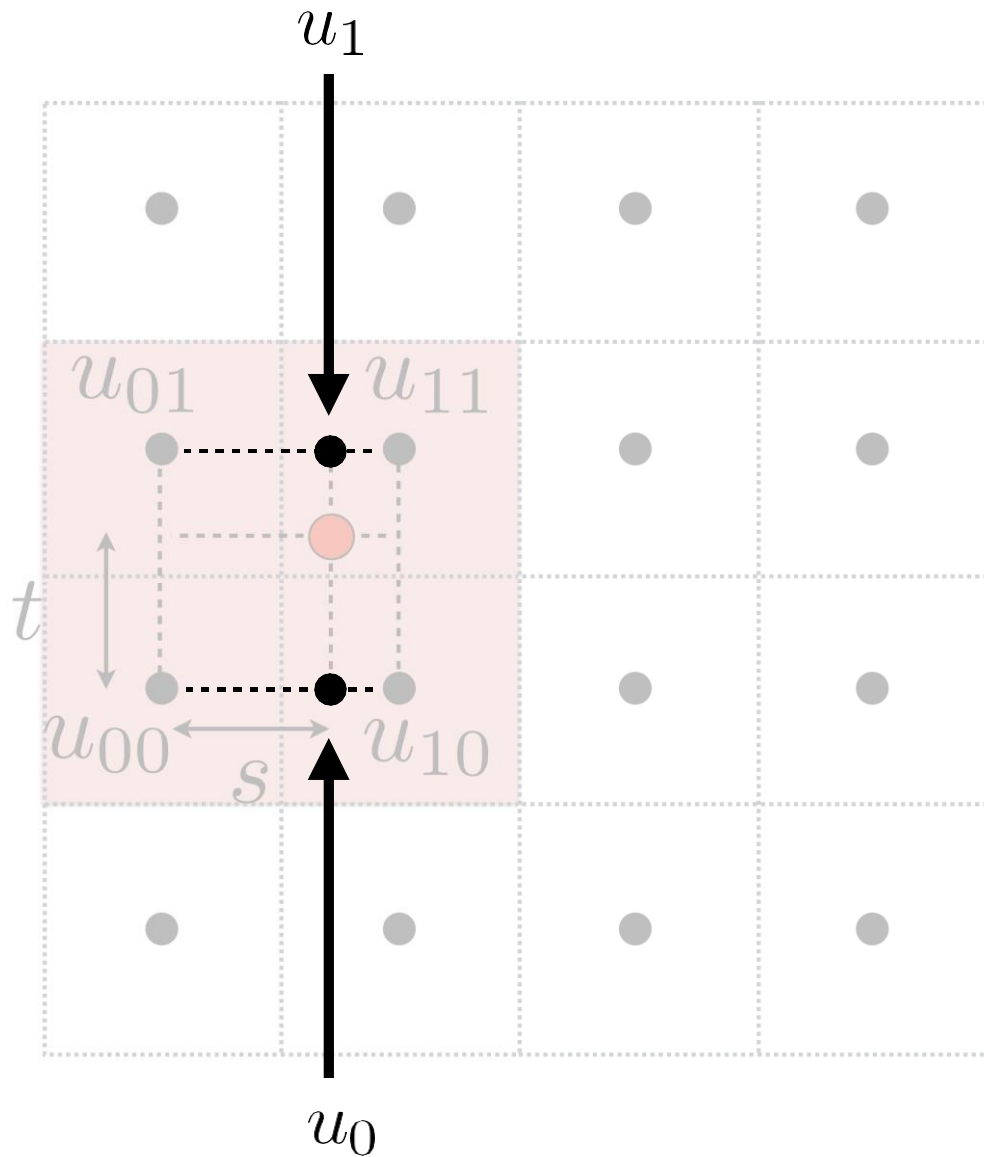
# Bilinear Interpolation



Linear interpolation (1D)

$$\text{lerp}(x, v_0, v_1) = v_0 + x(v_1 - v_0)$$

# Bilinear Interpolation



Linear interpolation (1D)

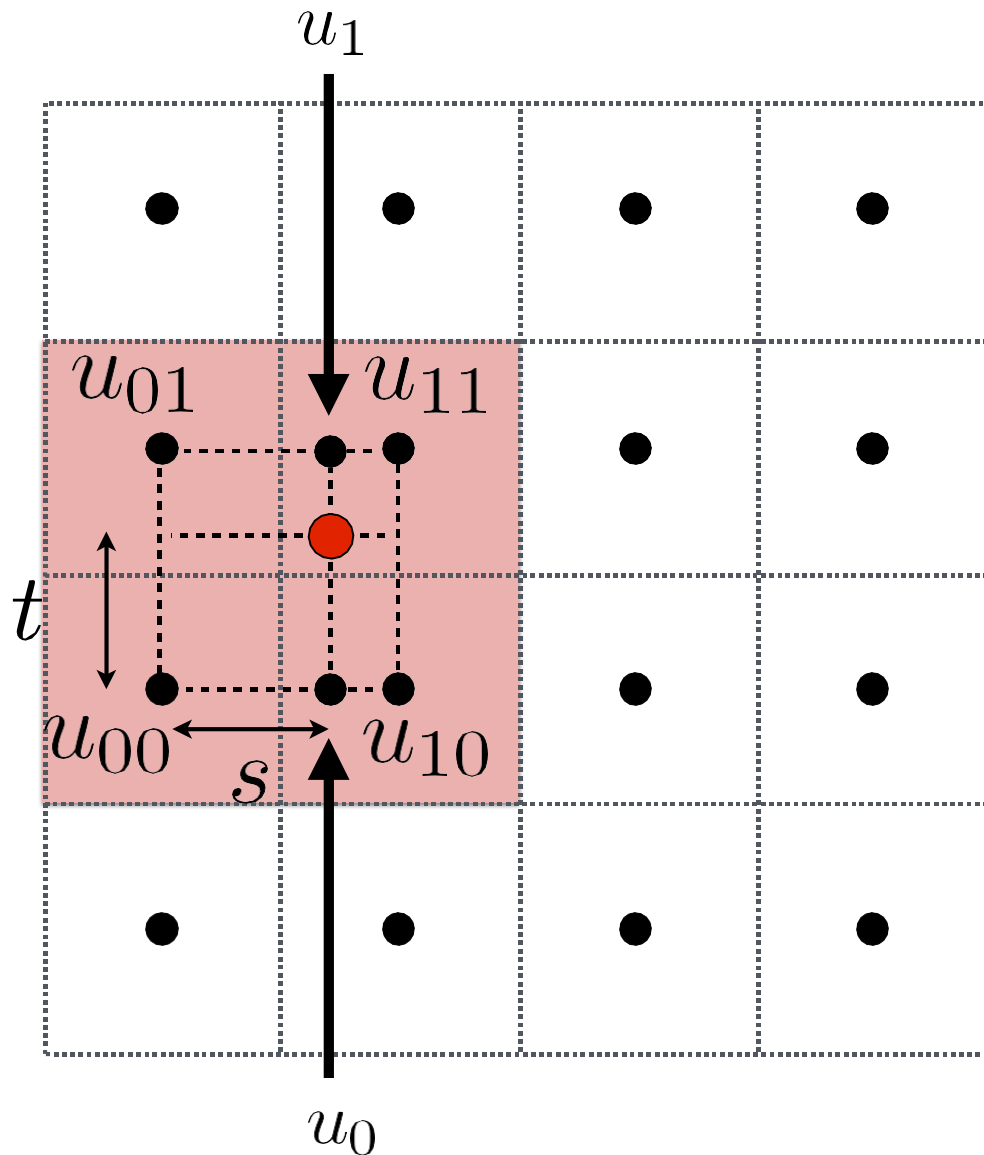
$$\text{lerp}(x, v_0, v_1) = v_0 + x(v_1 - v_0)$$

Two helper lerps (horizontal)

$$u_0 = \text{lerp}(s, u_{00}, u_{10})$$

$$u_1 = \text{lerp}(s, u_{01}, u_{11})$$

# Bilinear Interpolation



Linear interpolation (1D)

$$\text{lerp}(x, v_0, v_1) = v_0 + x(v_1 - v_0)$$

Two helper lerps

$$u_0 = \text{lerp}(s, u_{00}, u_{10})$$

$$u_1 = \text{lerp}(s, u_{01}, u_{11})$$

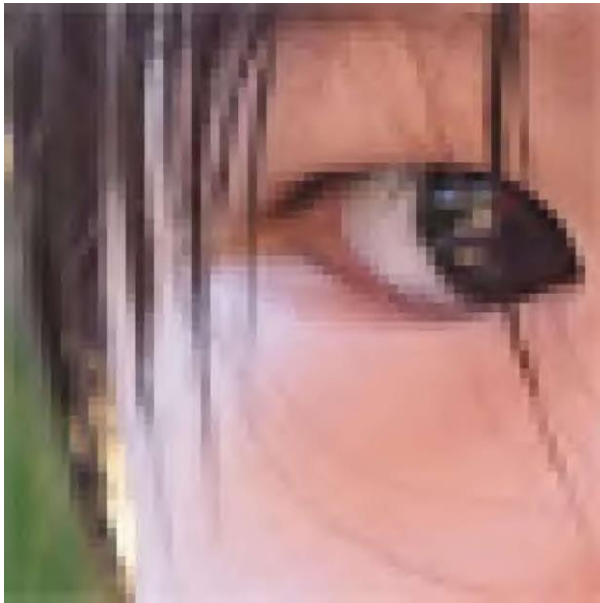
Final vertical lerp, to get result:

$$f(x, y) = \text{lerp}(t, u_0, u_1)$$

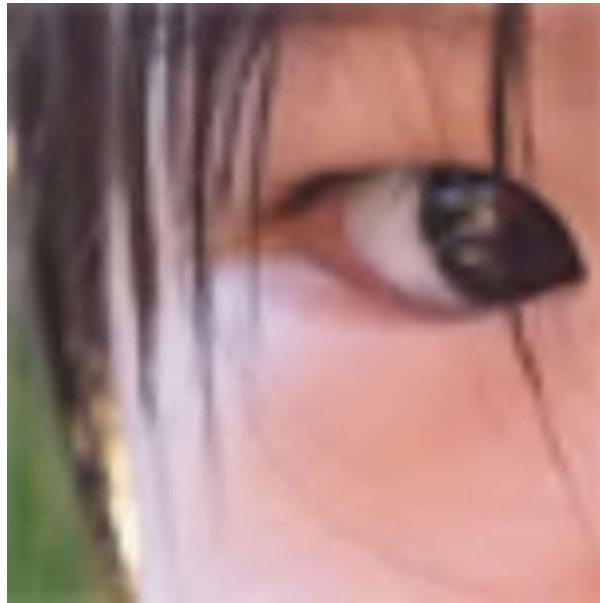
演示权重的推导?

# Texture Magnification - Easy Case

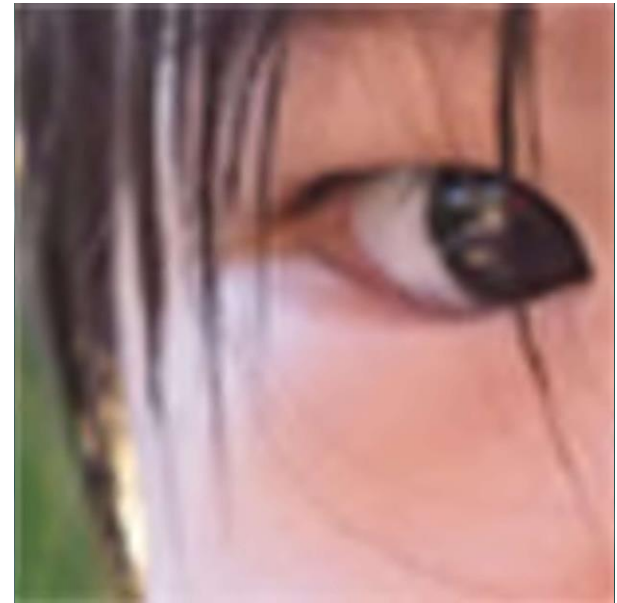
Bilinear interpolation usually gives pretty good results at reasonable costs



Nearest



Bilinear

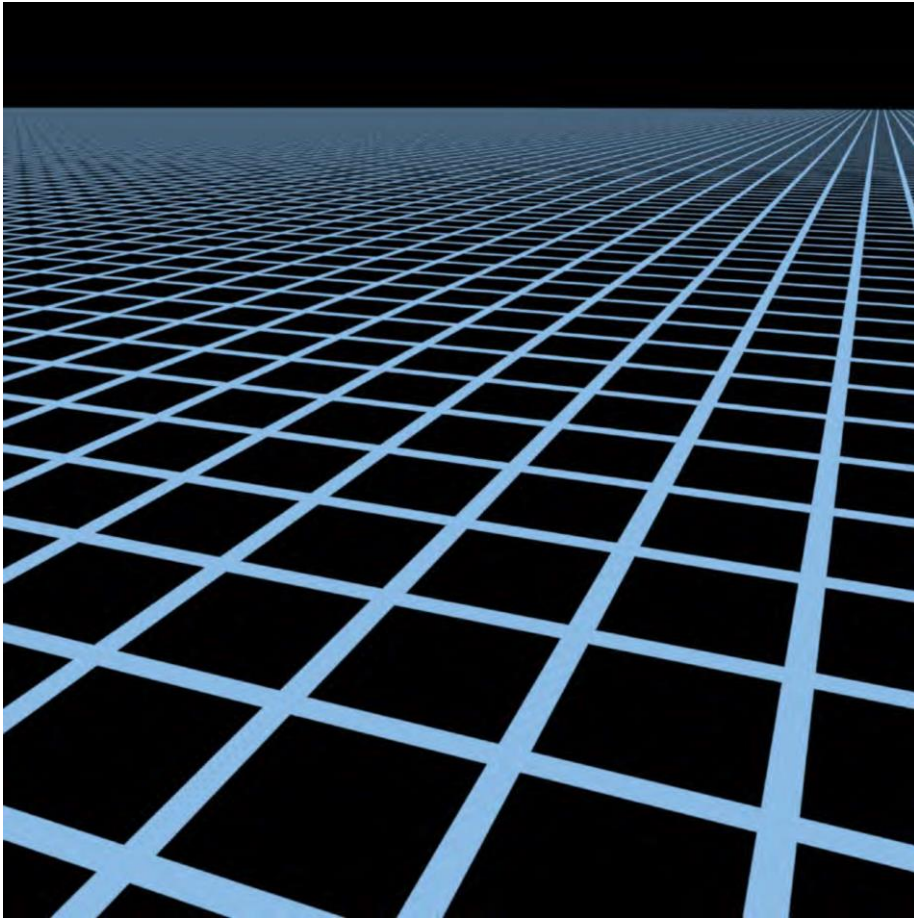


Bicubic

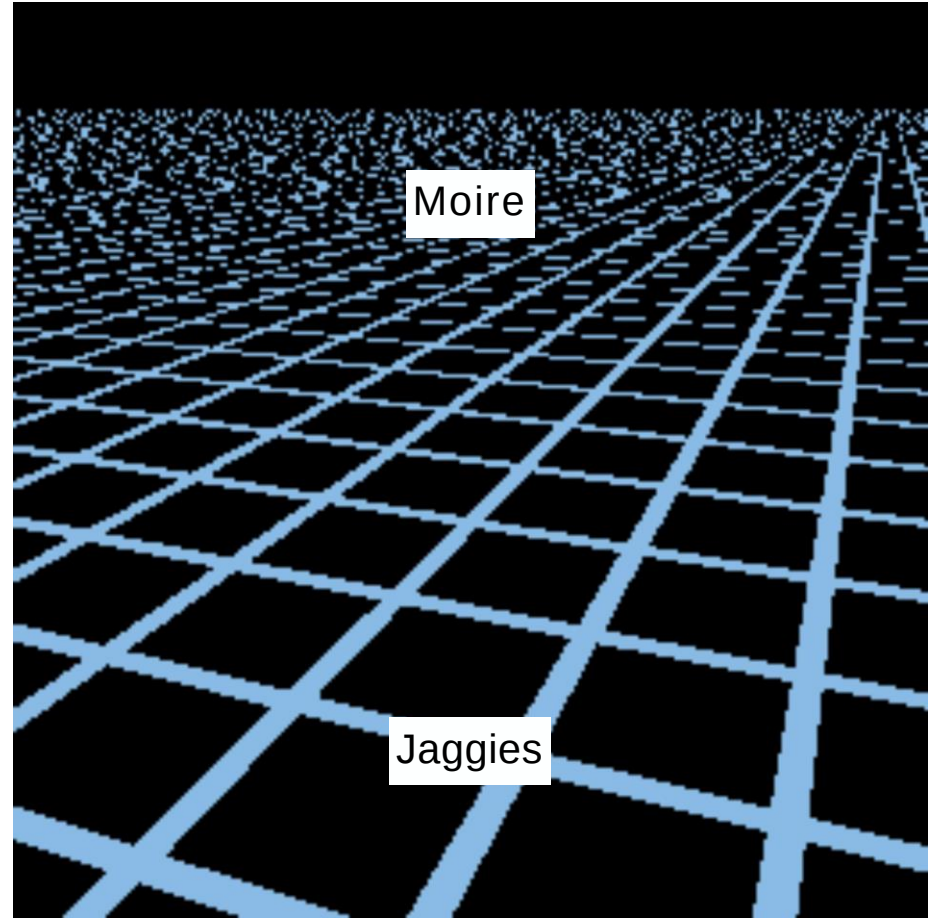
# Texture Magnification (hard case)

(What if the texture is too large?)

# Point Sampling Textures — Problem

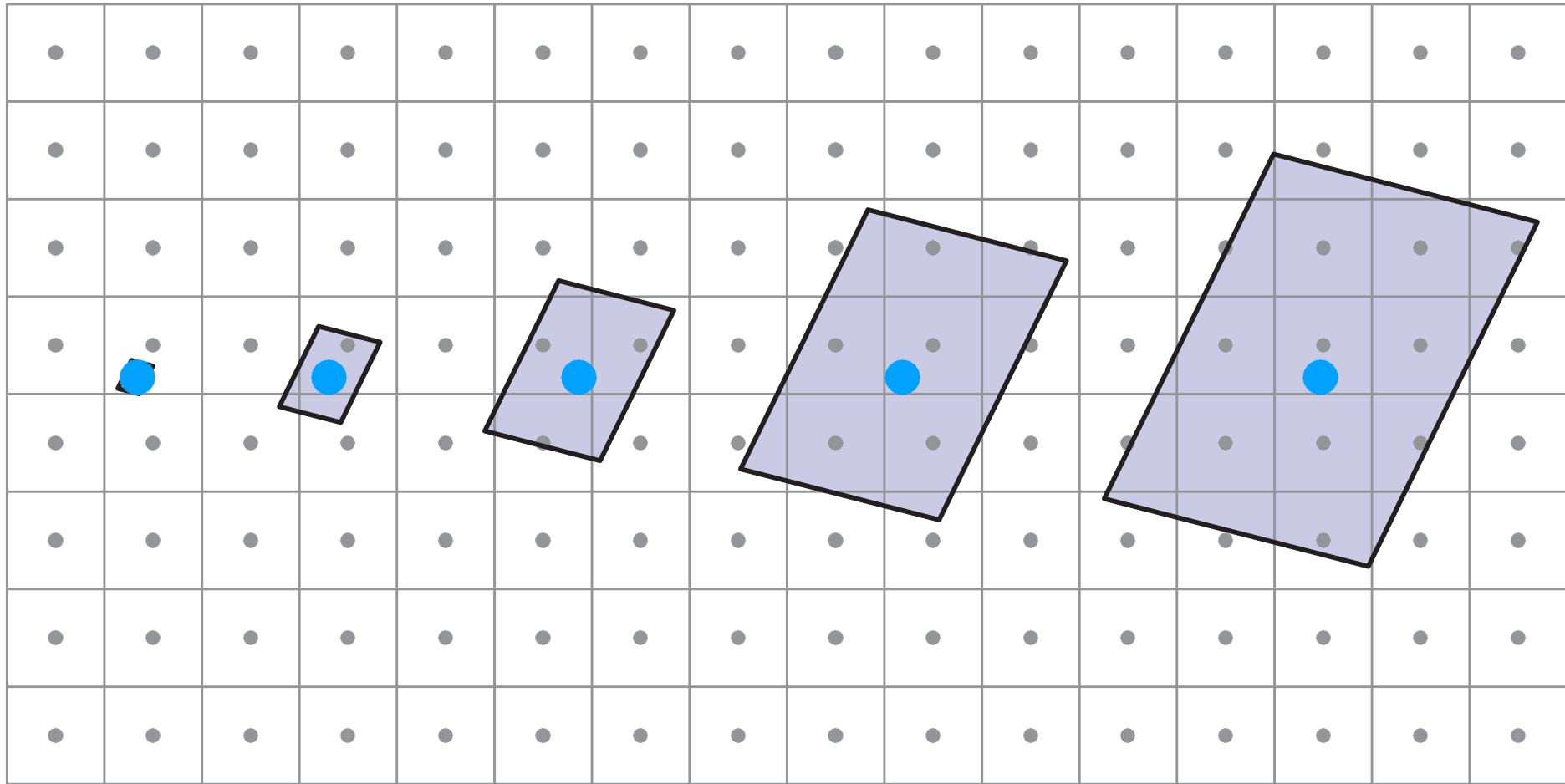


Reference



Point sampled

# Screen Pixel “Footprint” in Texture

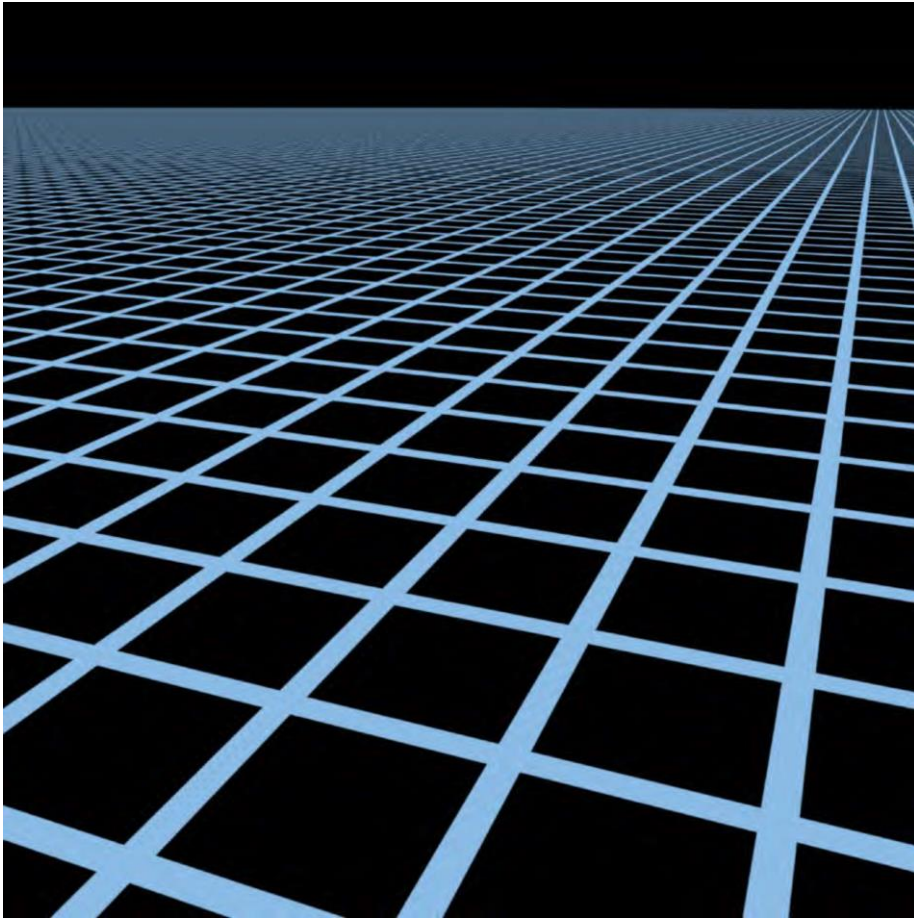


Upsampling  
(Magnification)



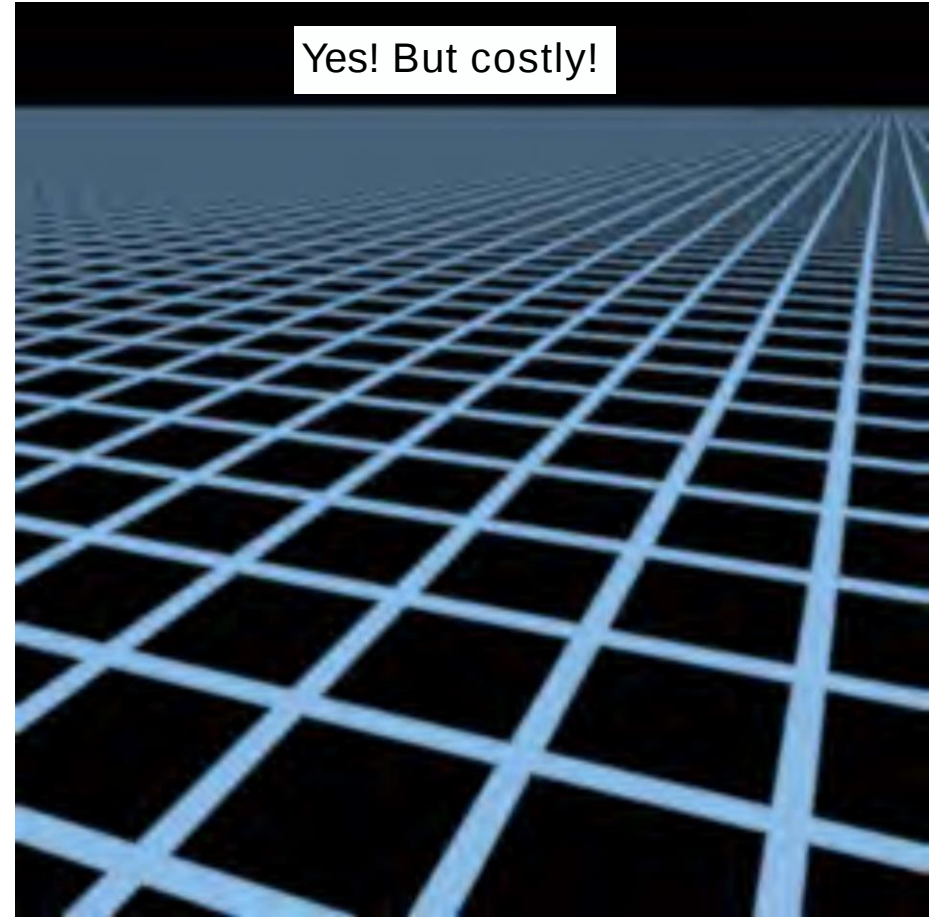
Downsampling  
(Minification)

# Will Supersampling Do Antialiasing?



Multisample Anti-Aliasing  
(MSAA)

多重采样抗锯齿



512x supersampling

# Antialiasing — Supersampling?

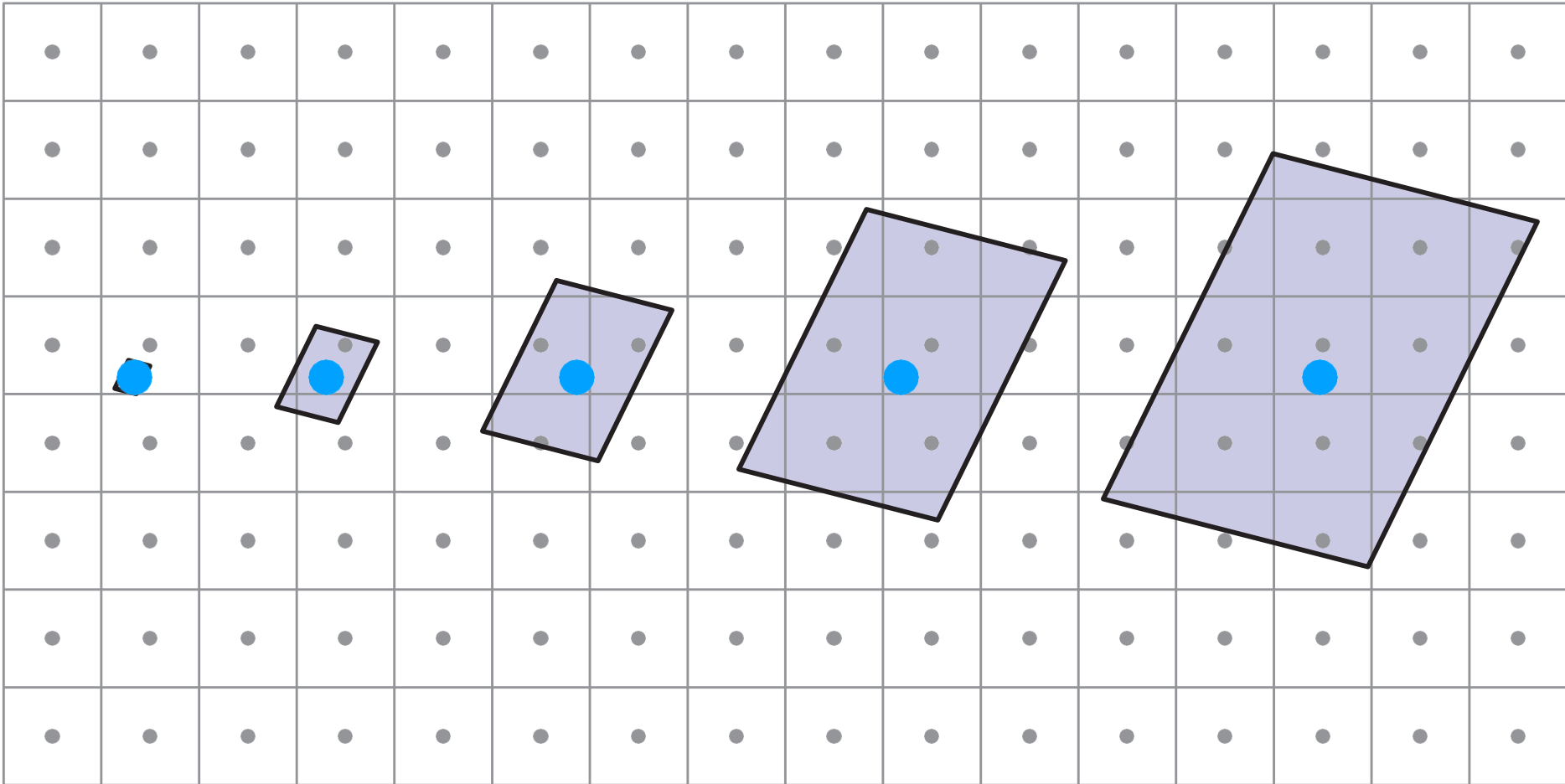
Will supersampling work?

- Yes, high quality, but costly
- When highly minified, many texels in pixel footprint
- Signal frequency too large in a pixel
- Need even higher sampling frequency

Let's understand this problem in another way

- What if we don't sample?
- Just need to get the average value within a range!

# Point Query vs. (Avg.) Range Query



# Different Pixels -> Different-Sized Footprints



# Mipmap

Allowing (fast, approx., square) range queries

# Mipmap (L. Williams 83)

“Mip” comes from the Latin “multum in parvo”, meaning a multitude in a small space



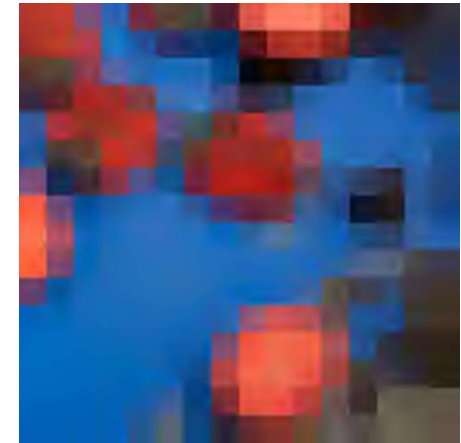
Level 0 = 128x128



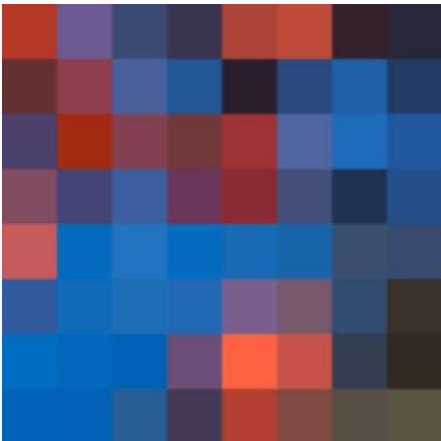
Level 1 = 64x64



Level 2 = 32x32



Level 3 = 16x16



Level 4 = 8x8



Level 5 = 4x4

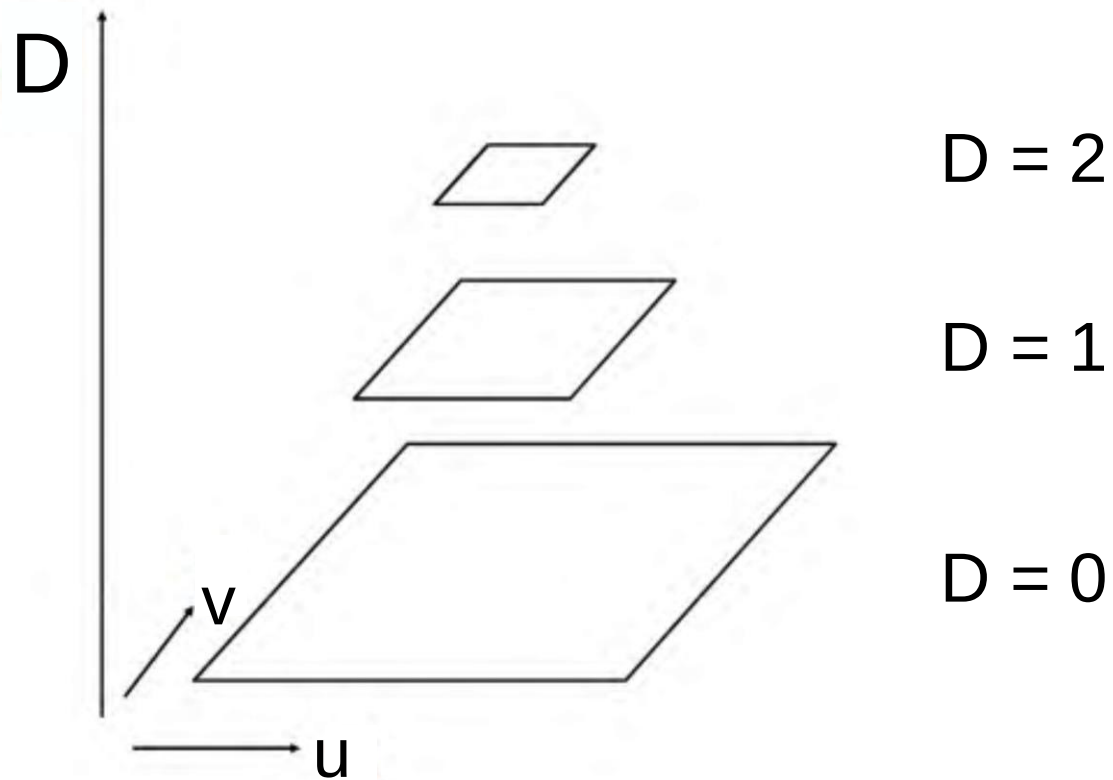


Level 6 = 2x2



Level 7 = 1x1

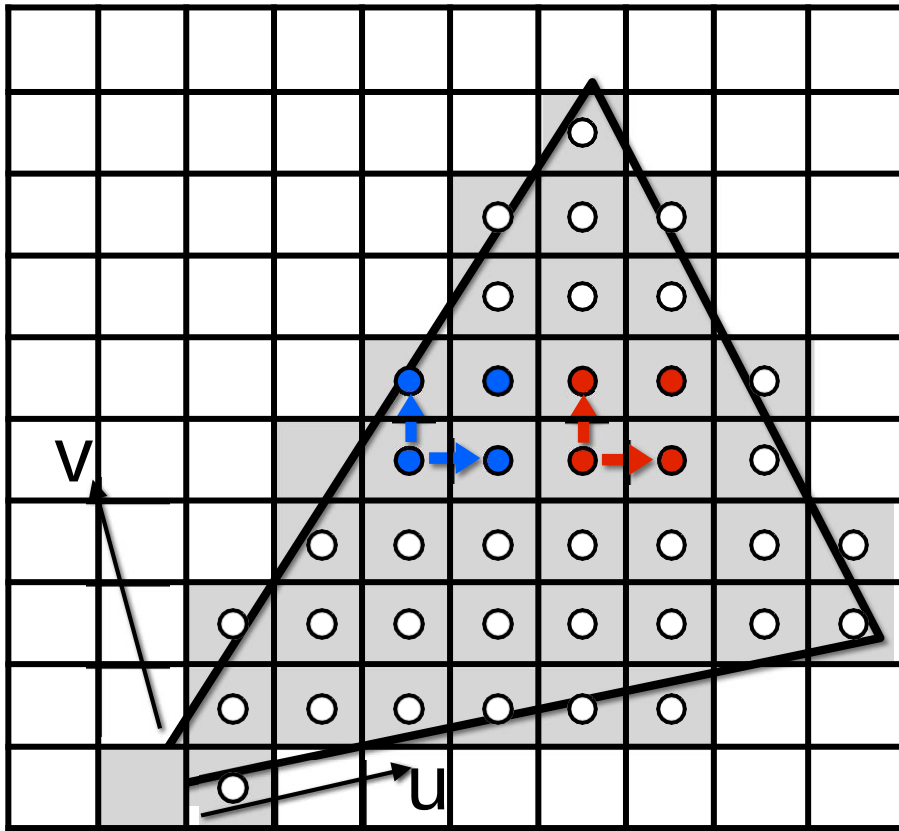
# Mipmap (L. Williams 83)



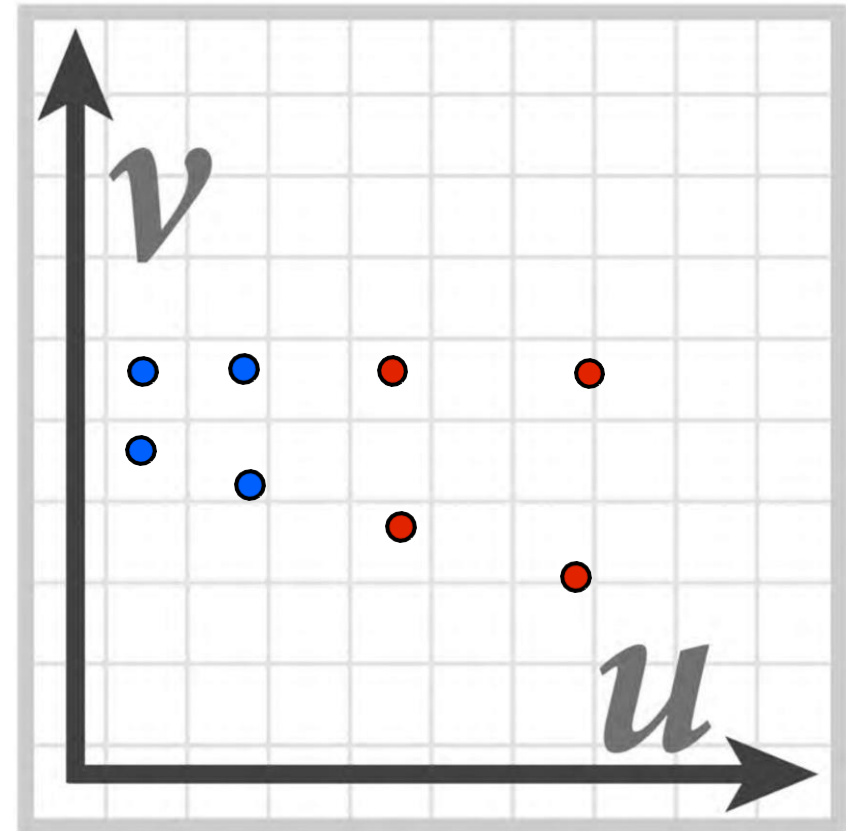
“Mip hierarchy”  
level =  $D$

What is the storage overhead of a mipmap?

# Computing Mipmap Level D



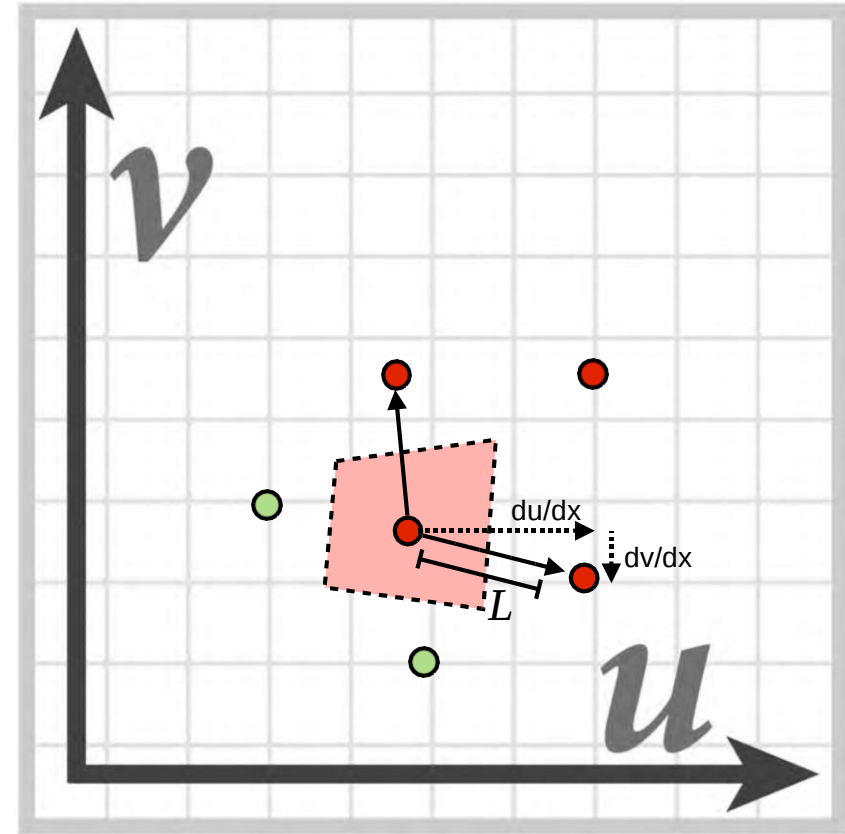
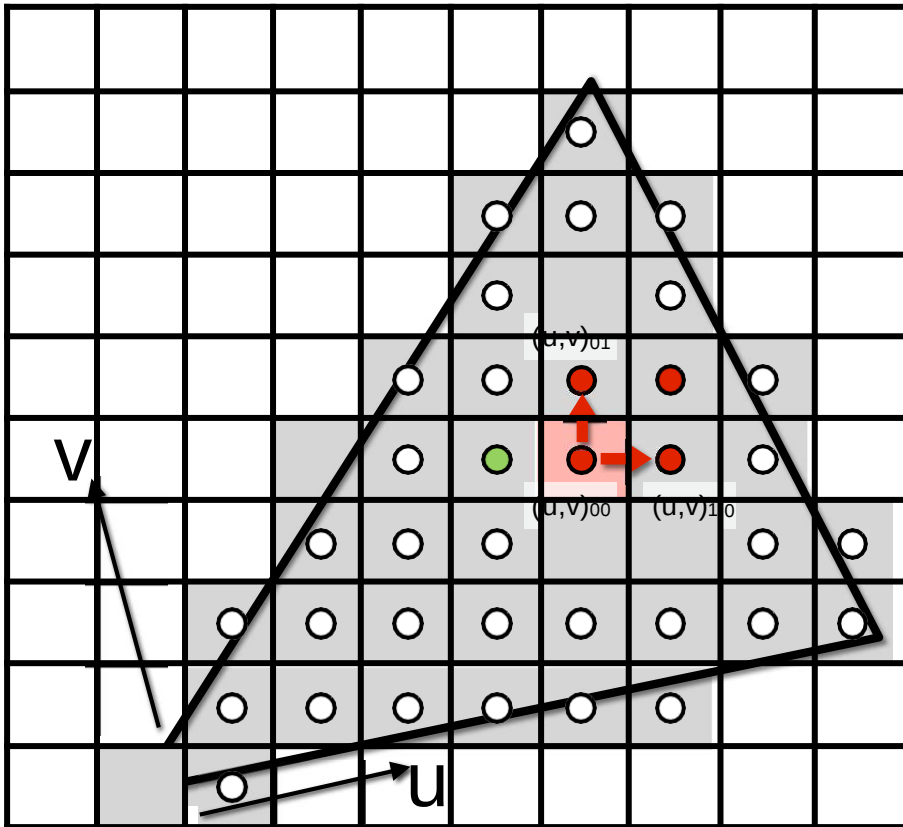
Screen space (x,y)



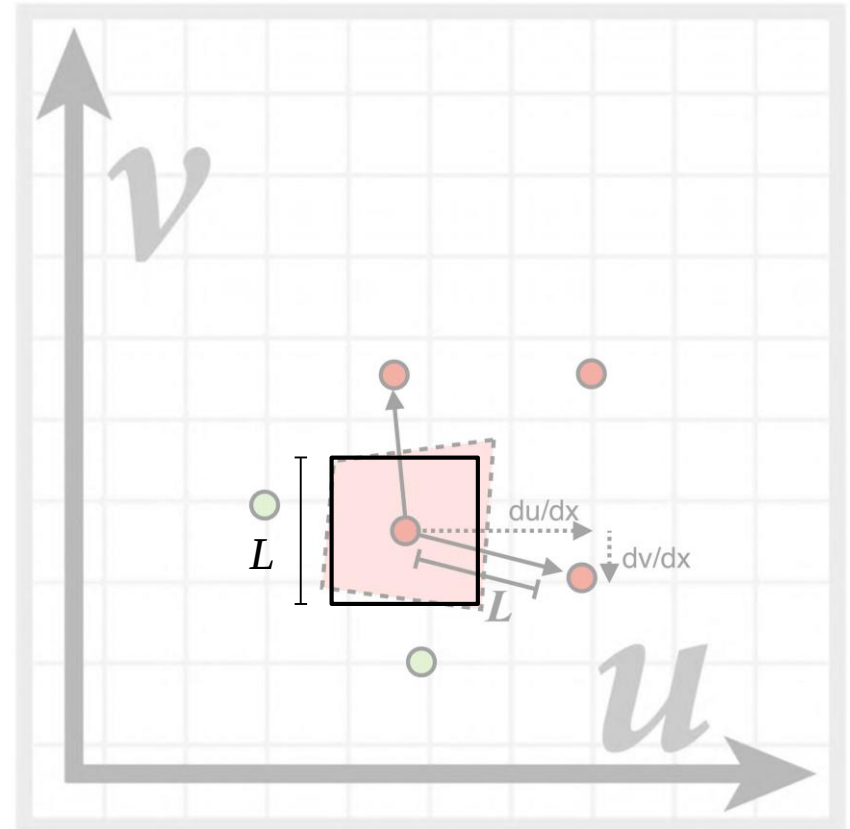
Texture space (u,v)

Estimate texture footprint using texture coordinates of neighboring screen samples

# Computing Mipmap Level D

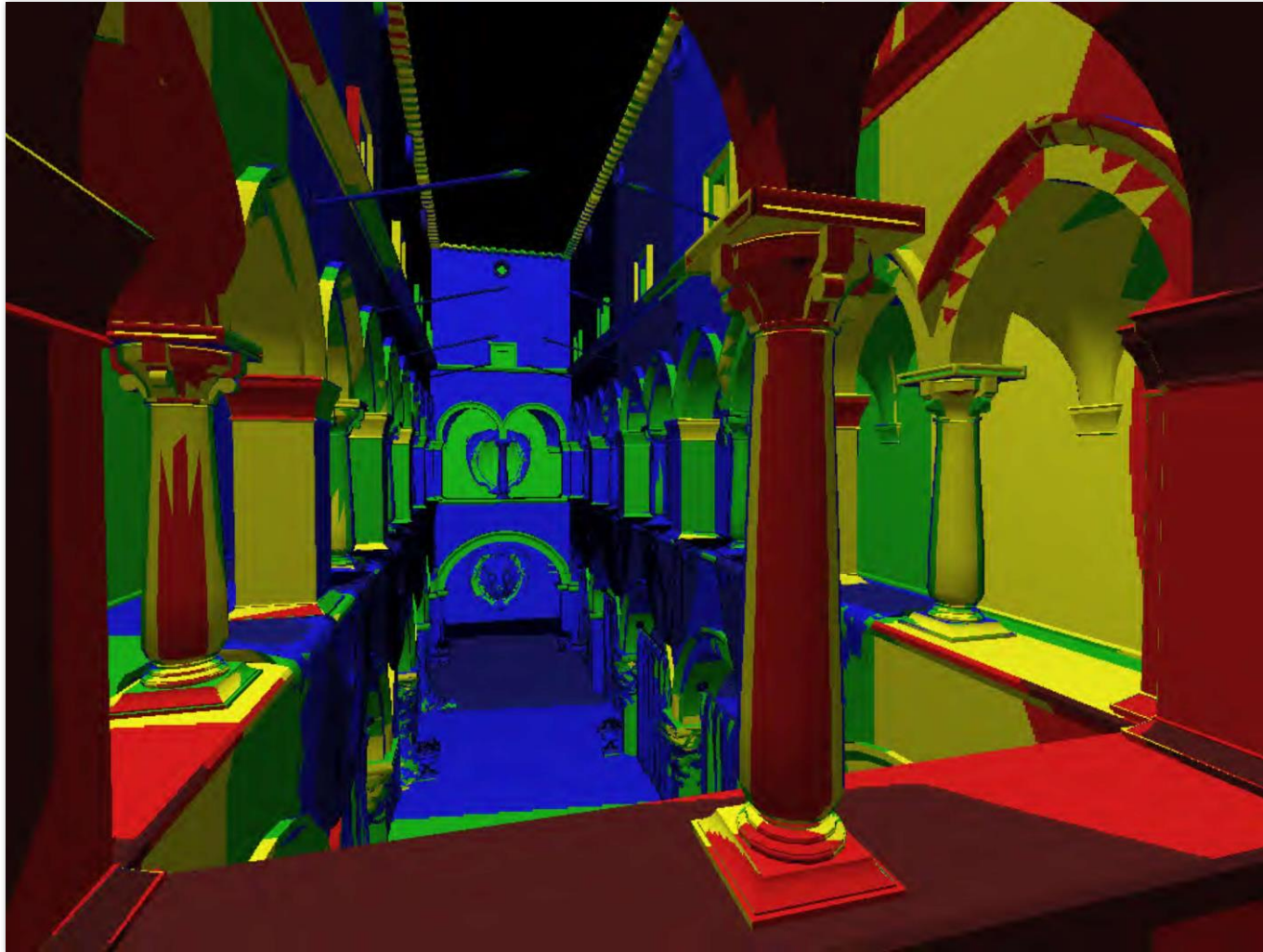


$$D = \log_2 L \quad L = \max \left( \sqrt{\left(\frac{du}{dx}\right)^2 + \left(\frac{dv}{dx}\right)^2}, \sqrt{\left(\frac{du}{dy}\right)^2 + \left(\frac{dv}{dy}\right)^2} \right)$$



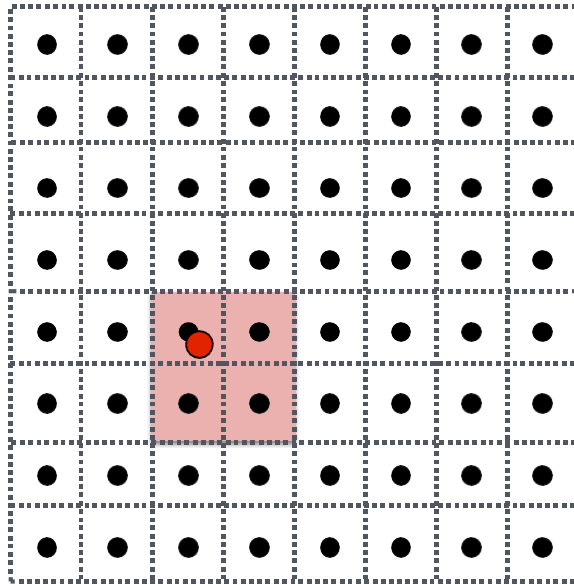
49

# Visualization of Mipmap Level



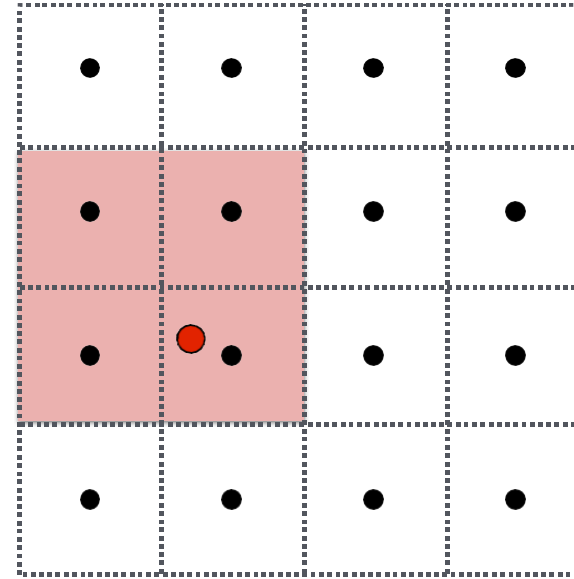
D rounded to nearest integer level

# Trilinear Interpolation



Mipmap Level D

Bilinear result

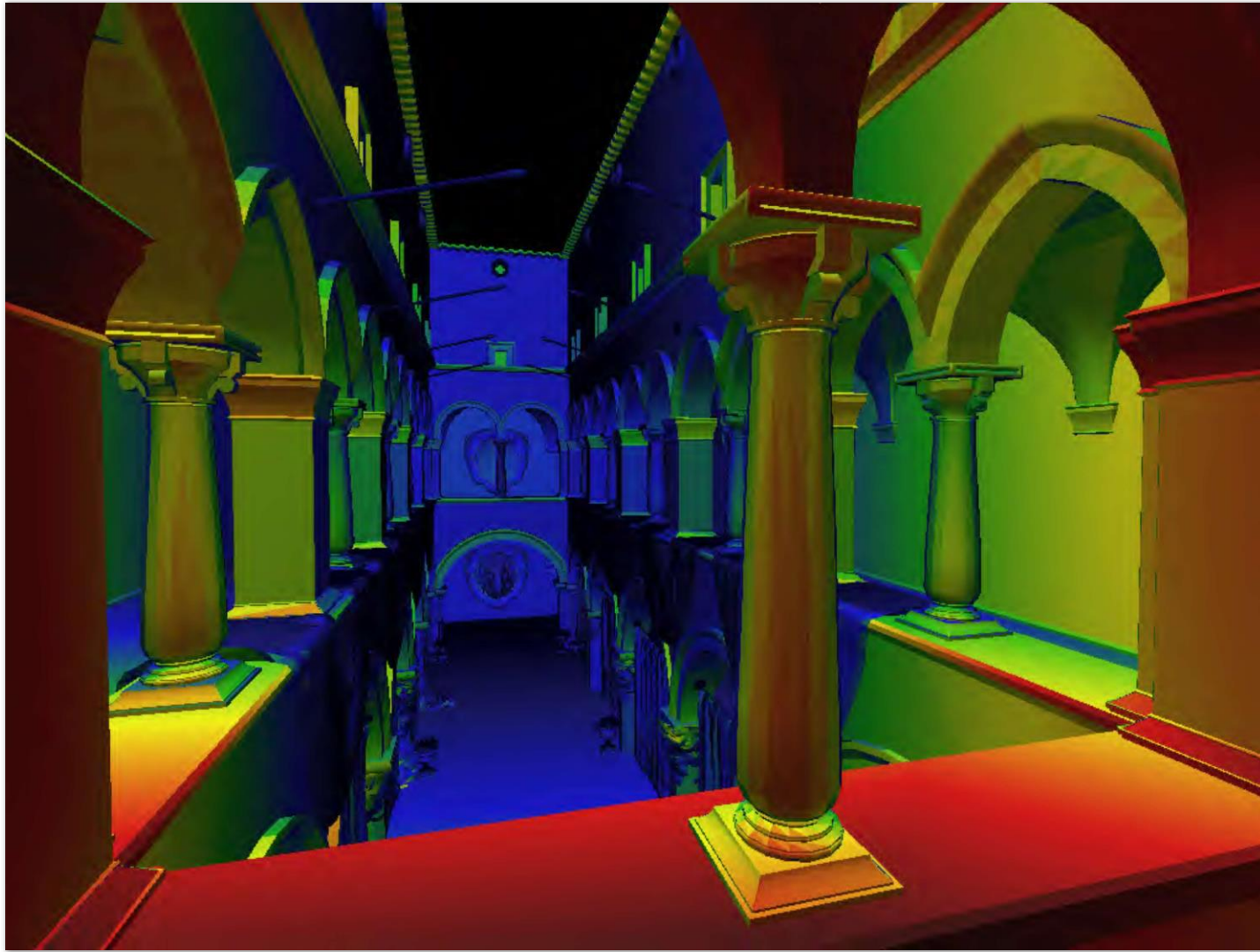


Mipmap Level D+1

Bilinear result

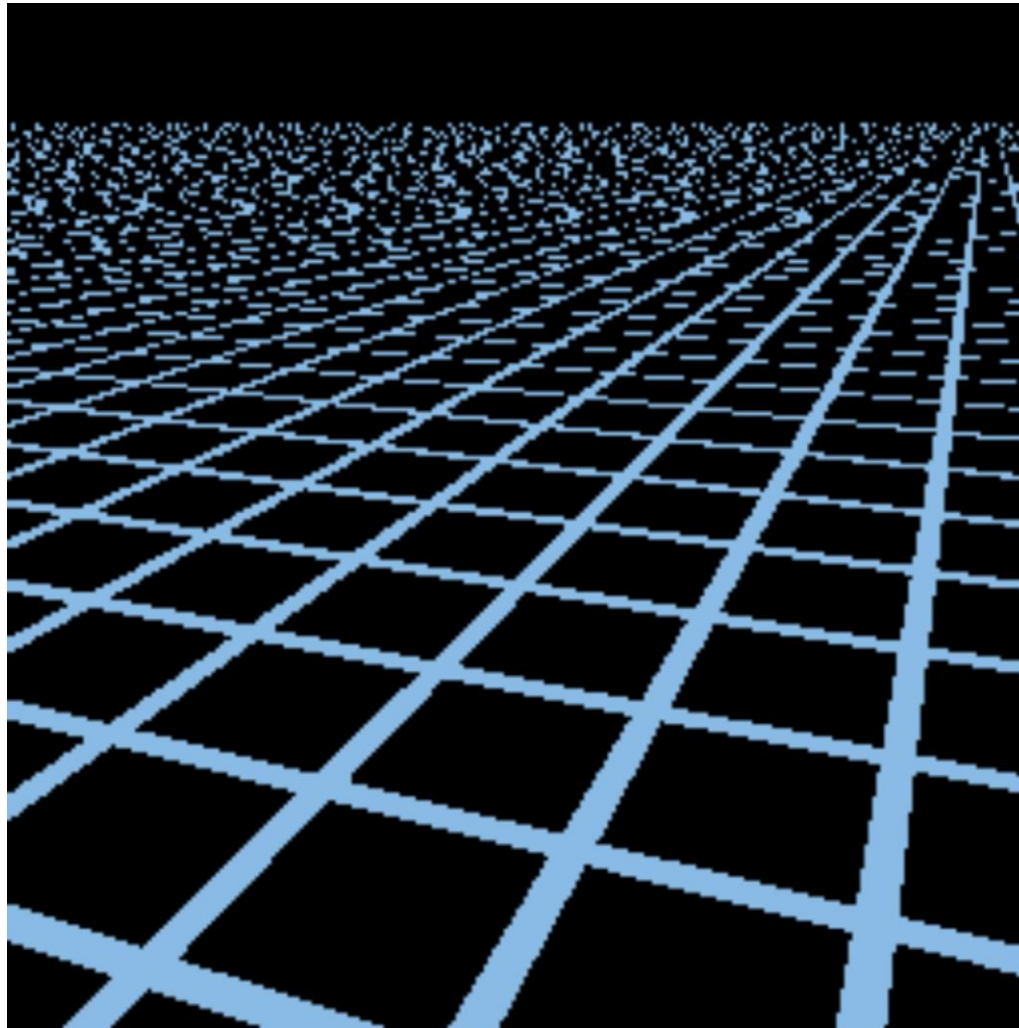
Linear interpolation based on continuous D value

# Visualization of Mipmap Level



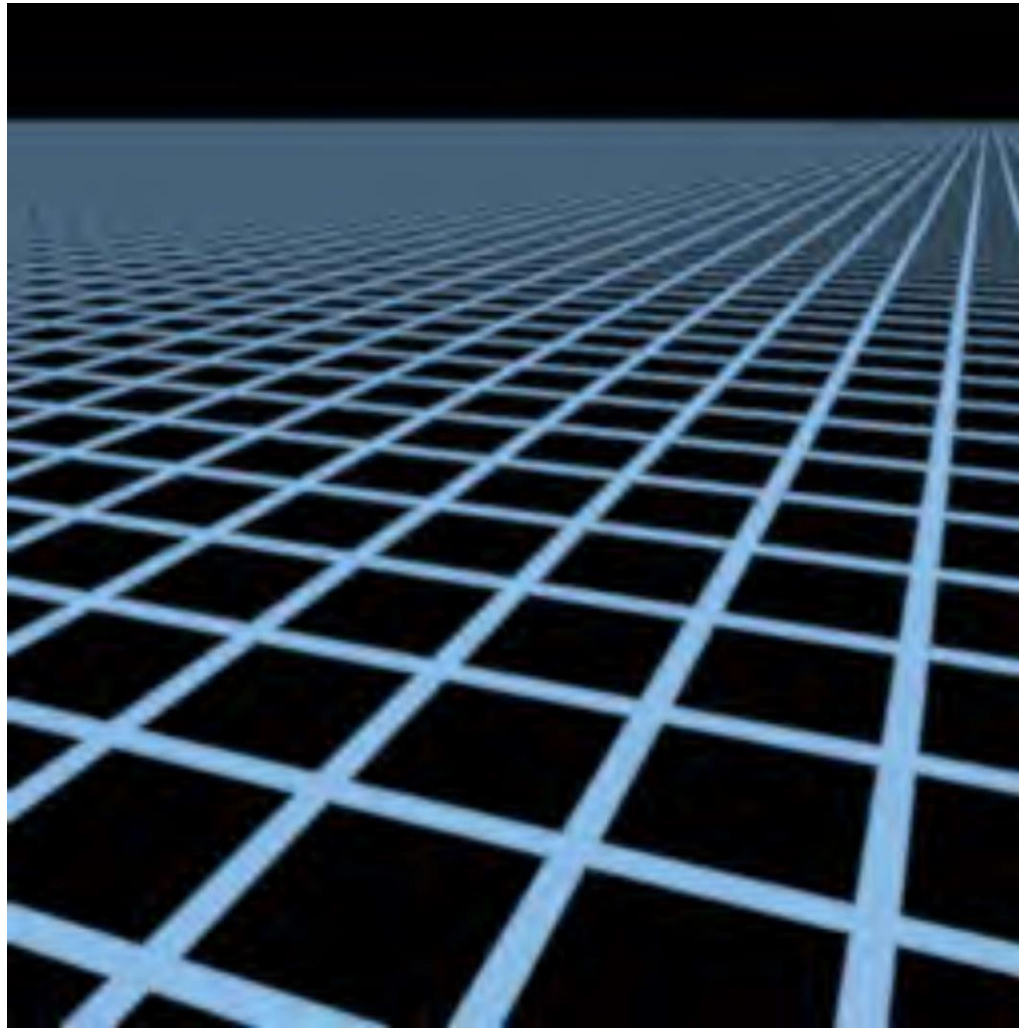
Trilinear filtering: visualization of continuous D

# Mipmap Limitations



Point sampling

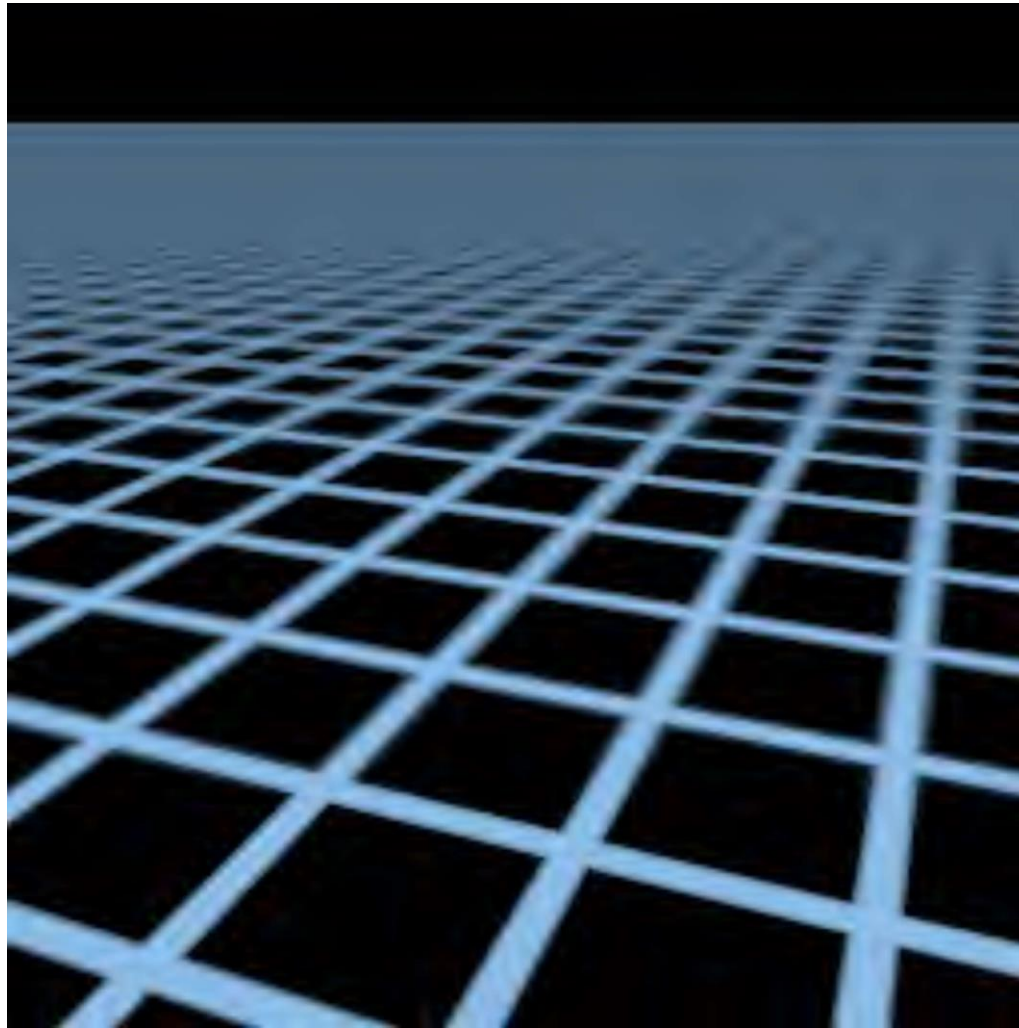
# Mipmap Limitations



Supersampling 512x (assume this is correct)

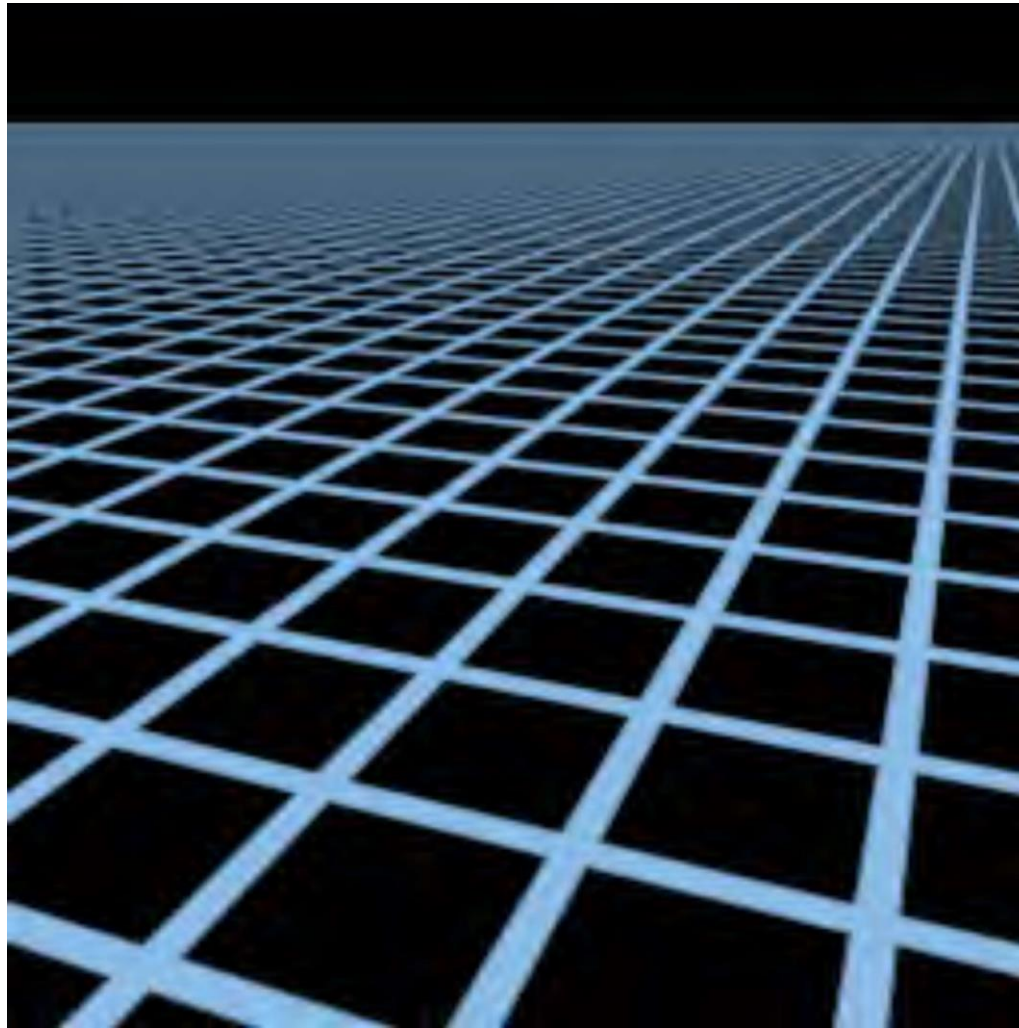
# Mipmap Limitations

Overblur  
Why?



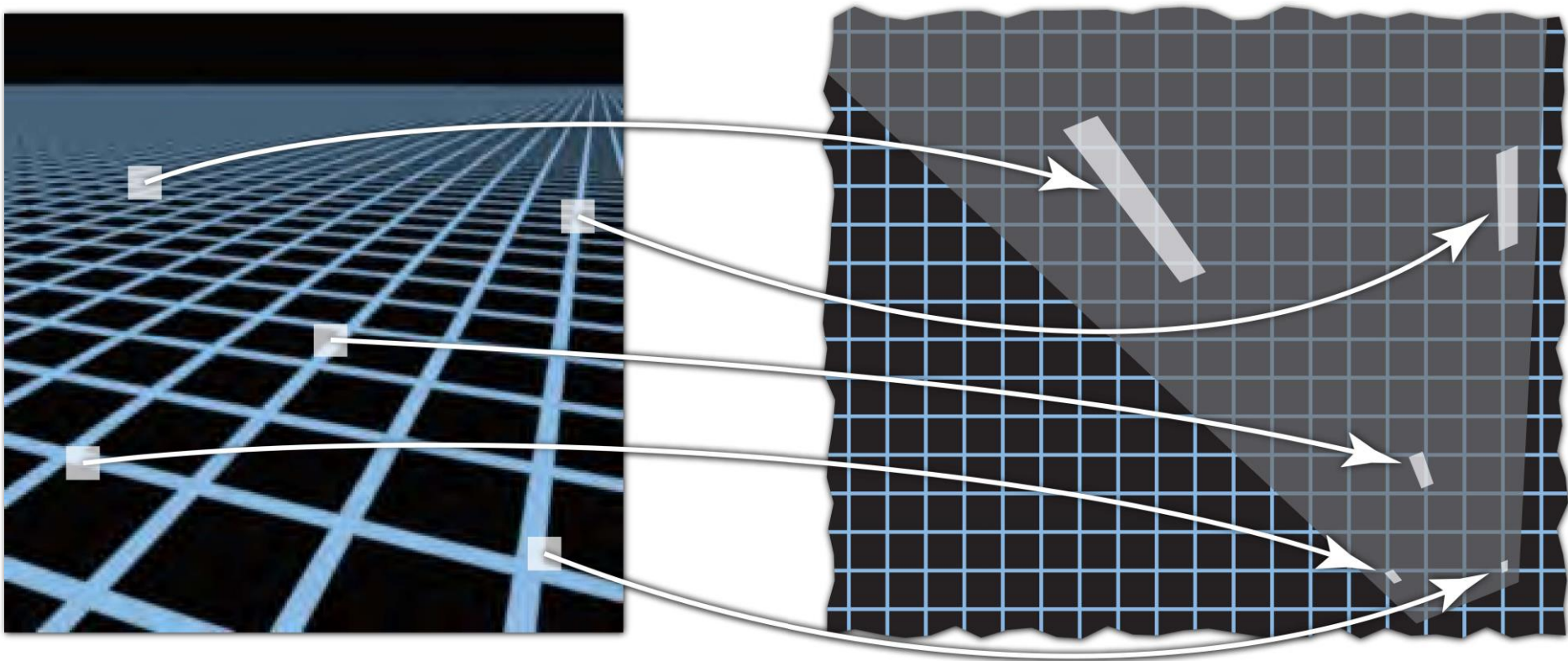
Mipmap trilinear sampling

# Anisotropic Filtering



Better than Mipmap!

# Irregular Pixel Footprint in Texture



Screen space

Texture space

# Anisotropic Filtering

Ripmaps and summed area tables

- Can look up axis-aligned rectangular zones
- Diagonal footprints still a problem



Wikipedia

# Anisotropic Filtering

Ripmaps and summed area tables

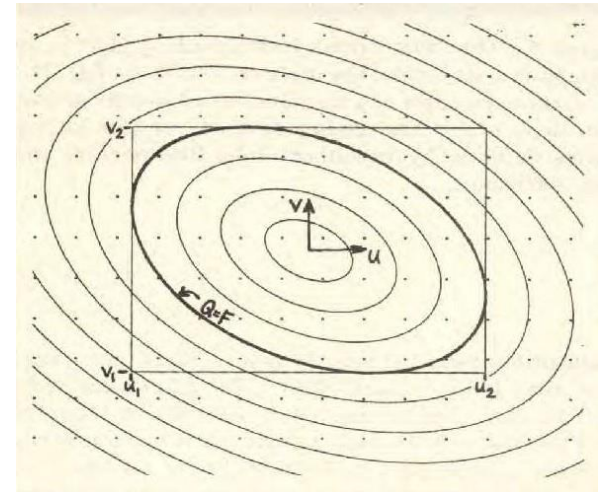
- Can look up axis-aligned rectangular zones
- Diagonal footprints still a problem



Wikipedia

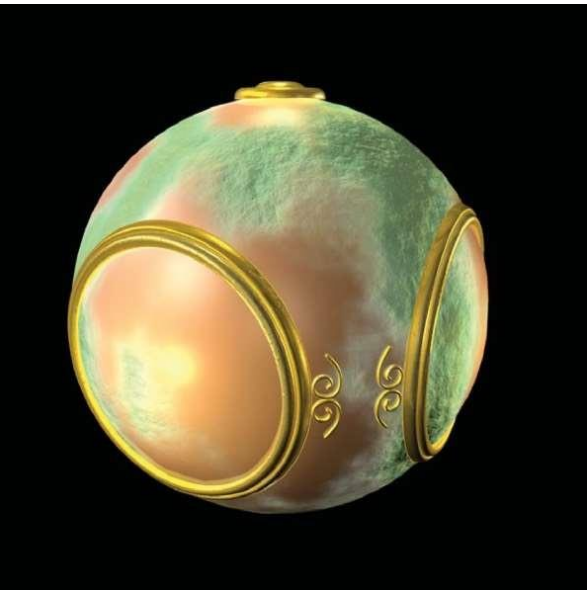
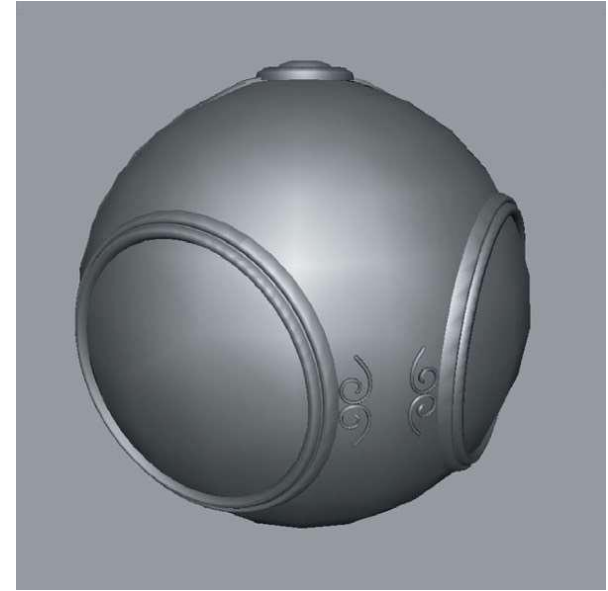
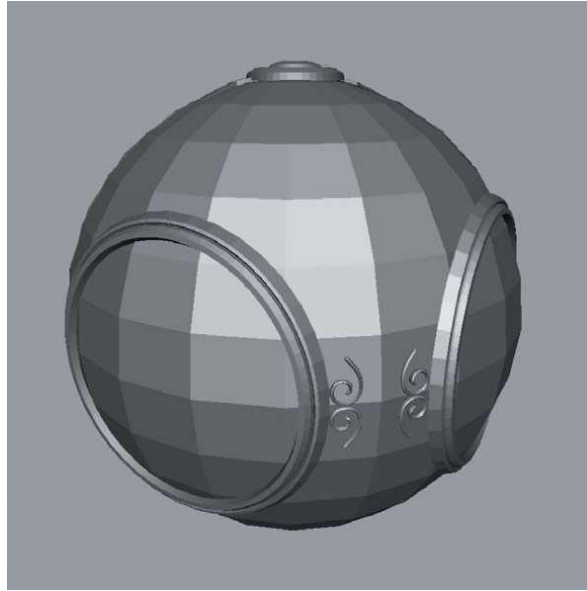
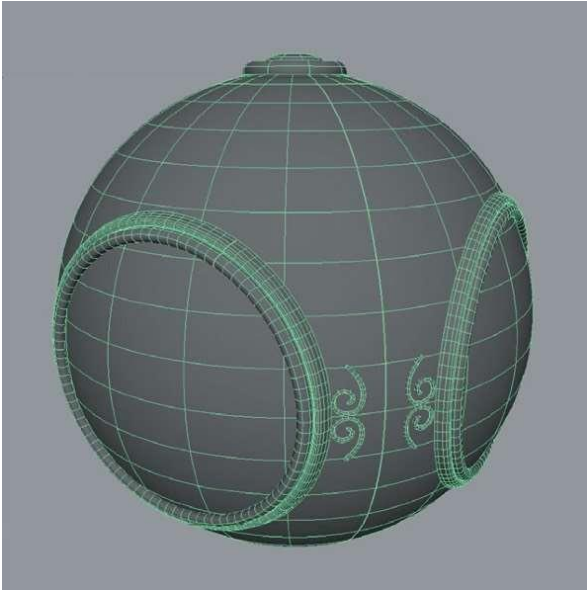
EWA filtering

- Use multiple lookups
- Weighted average
- Mipmap hierarchy still helps
- Can handle irregular footprints



Greene & Heckbert '86

# Last Lectures



today

# Applications of Textures

# Many, Many Uses for Texturing

In modern GPUs, texture = memory + range query (filtering)

- General method to bring data to fragment calculations

Many applications

- Environment lighting
- Store microgeometry
- Procedural textures
- Solid modeling
- Volume rendering
- ...

# Environment Map



Light from the environment



[Blinn & Newell 1976]

Rendering with the environment

# Environmental Lighting



Environment map (left) used to render realistic lighting

# Spherical Environment Map



*Hand with Reflecting Sphere.* M. C. Escher, 1935. lithograph



Eucalyptus Grove Light Probe  
©1999 Paul Debevec  
<http://www.debevec.org/Probes>

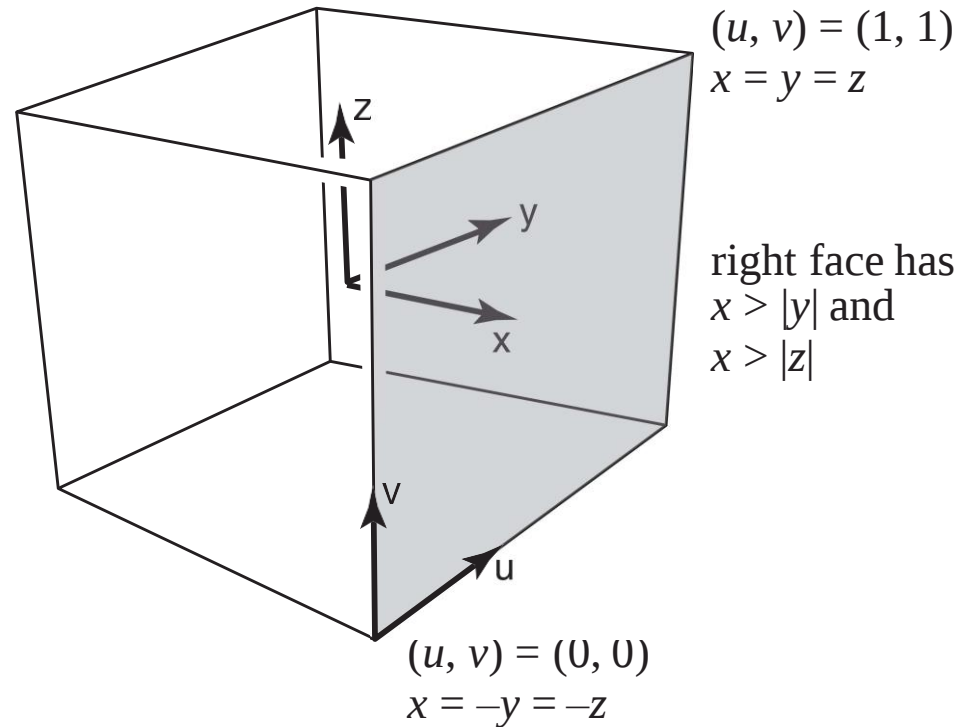
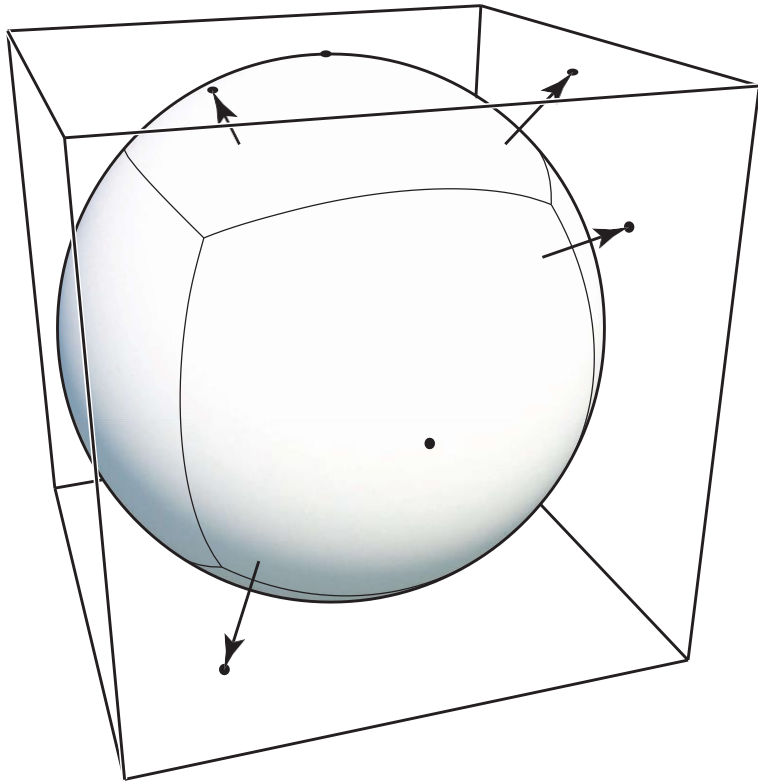
*Light Probes,* Paul Debevec

# Spherical Map — Problem

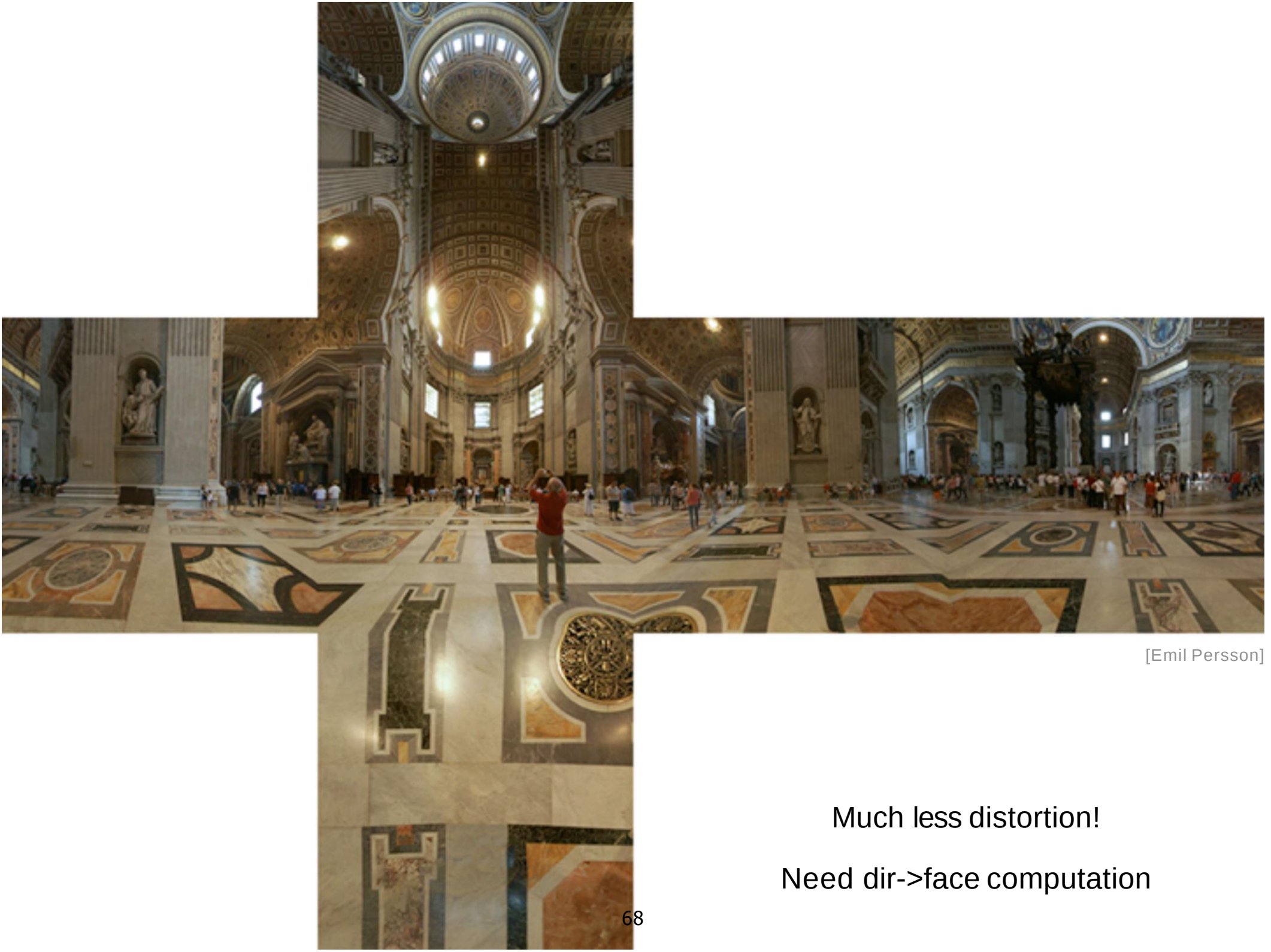


Prone to distortion (top and bottom parts)!

# Cube Map



A vector maps to cube point along that direction.  
The cube is textured with 6 square texture maps.

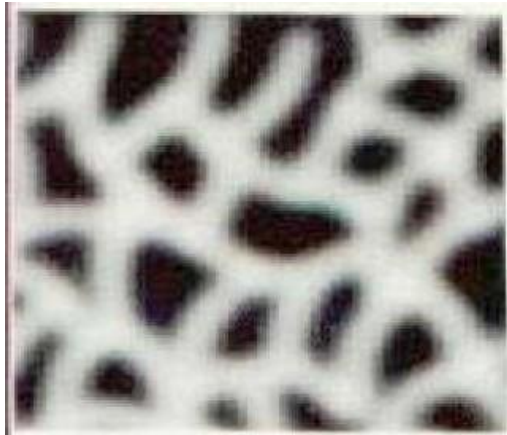


[Emil Persson]

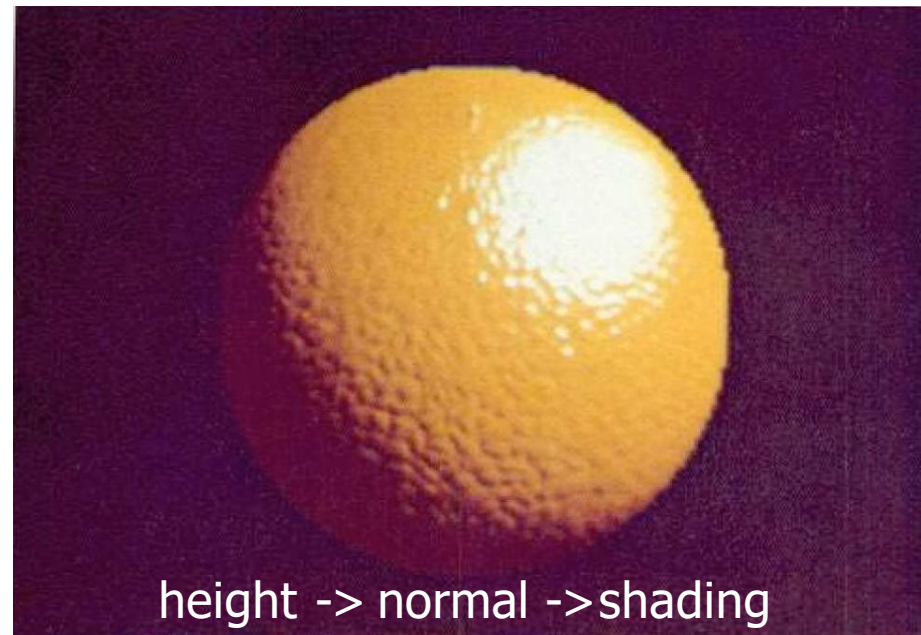
Much less distortion!  
Need dir->face computation

# Textures can affect shading!

- Textures doesn't have to only represent colors
  - What if it stores the height / normal?
  - Bump / normal mapping
  - Fake the detailed geometry



Relative height to the  
underlying surface

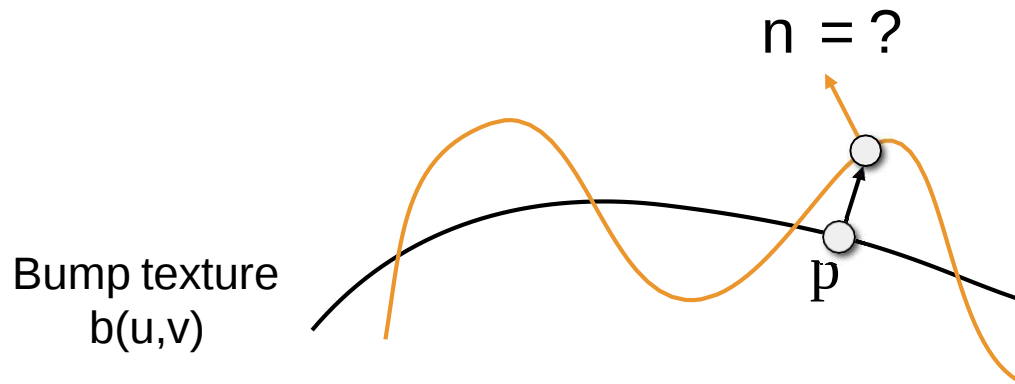


height -> normal -> shading

# Bump Mapping

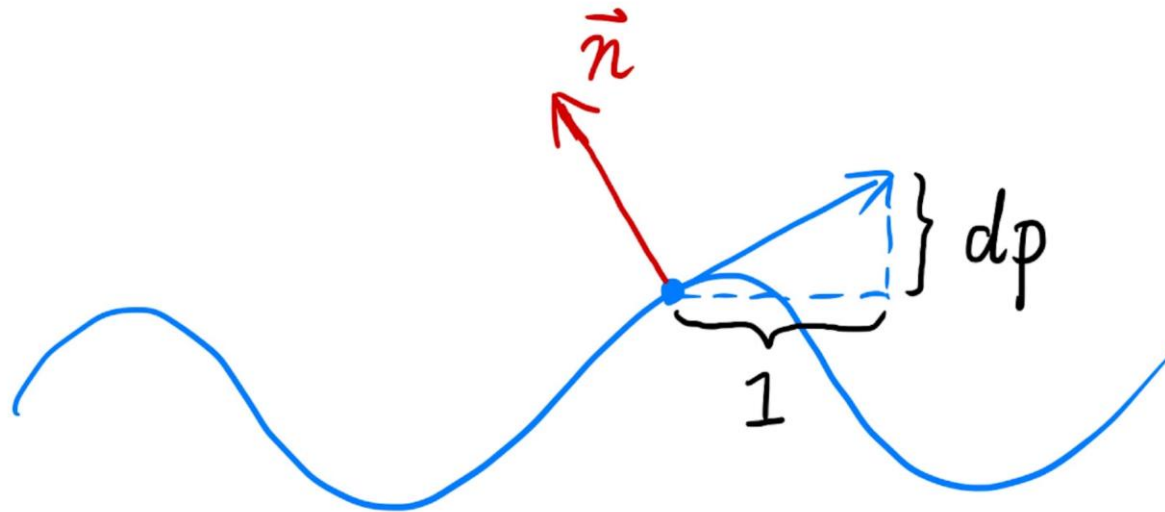
Adding surface detail without adding more triangles

- Perturb surface normal per pixel (for shading computations only)
- “Height shift” per texel defined by a texture
- How to modify normal vector?



# How to perturb the normal (in flatland)

- Original surface normal  $n(p) = (0, 1)$
- Derivative at  $p$  is  $dp = c * [h(p+1) - h(p)]$
- Perturbed normal is then  $n(p) = (-dp, 1).normalized()$

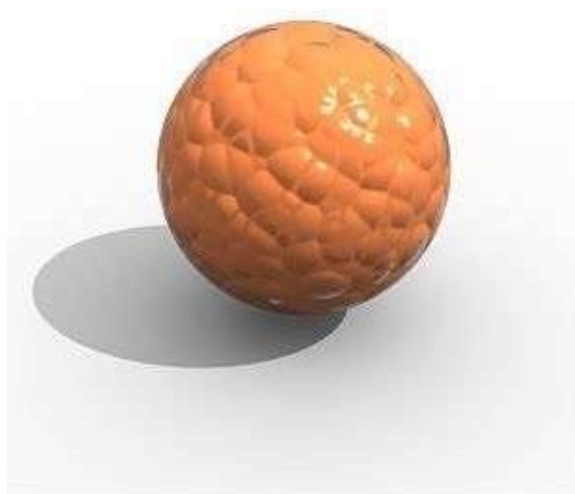


# How to perturb the normal (in 3D)

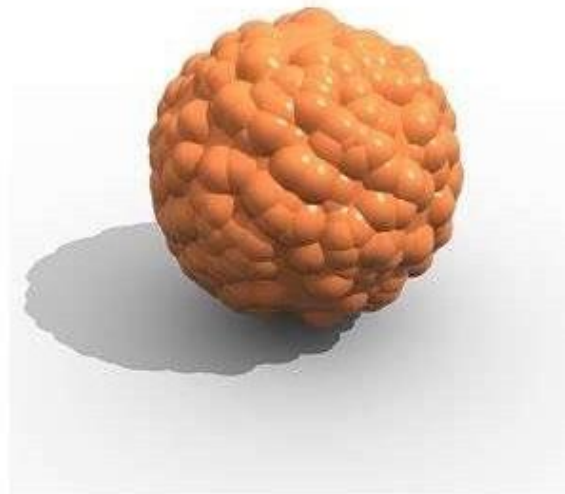
- Original surface normal  $n(p) = (0, 0, 1)$
- Derivatives at  $p$  are
  - $dp/du = c1 * [h(u+1) - h(u)]$
  - $dp/dv = c2 * [h(v+1) - h(v)]$
- Perturbed normal is  $n = (-dp/du, -dp/dv, 1).normalized()$
- Note that this is in local coordinate!  
More will be elaborated in FAQ of HW3

# Textures can affect shading!

- Displacement mapping — a more advanced approach
  - Uses the same texture as in bumping mapping
  - Actually moves the vertices

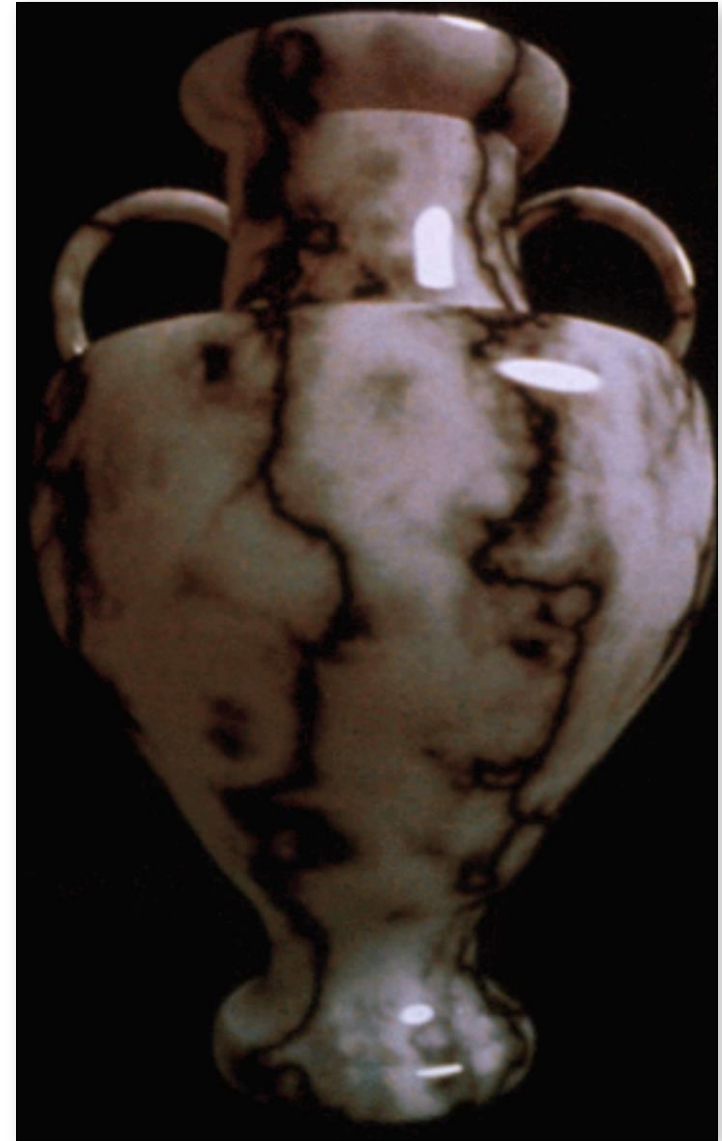


Bump / Normal mapping



Displacement mapping

# 3D Procedural Noise + Solid Modeling



Perlin noise, Ken Perlin

# Provide Precomputed Shading



Simple  
shading



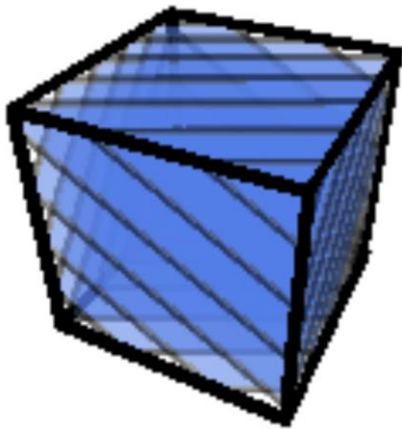
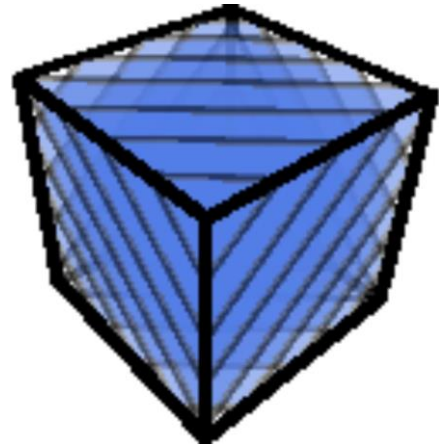
Ambient occlusion  
texture map



With ambient  
occlusion

Autodesk

# 3D Textures and Volume Rendering



Marc Levoy

Thank you!